# TOPOLOGICAL INVARIANTS AND MODULI SPACES OF GORENSTEIN QUASI-HOMOGENEOUS SURFACE SINGULARITIES

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ABSTRACT. We describe all connected components of the space of hyperbolic Gorenstein quasi-homogeneous surface singularities. We prove that any connected component is homeomorphic to a quotient of  $\mathbb{R}^d$  by a discrete group.

### 1. Introduction

In this paper we study moduli spaces of hyperbolic Gorenstein quasi-homogeneous surface singularities (GQHSS). A normal isolated singularity of dimension n is Gorenstein if and only if there is a nowhere vanishing n-form on a punctured neighbourhood of the singular point. GQHSS can be spherical, Euclidean or hyperbolic. In this paper we are going to study the largest class, the class of hyperbolic GQHSS. See a remark at the end of the paper for more information about the other two classes of GQHSS.

According to work of Dolgachev [Dol83b] hyperbolic GQHSS of level m are in 1-to-1 correspondence with m-th roots of tangent bundles of Riemann orbifolds, i.e. with (singular) complex line bundles on orbifolds such that their m-th tensor power coincides with the tangent bundle. We find conditions for the existence of GQHSS of level m with orbifold of given signature. We then consider the space of all GQHSS of level m with orbifolds of given signature and genus  $g \ge 0$ . We show that the space is connected if g = 0 or if g > 1 and m is odd and that the space has 2 connected components if g > 1 and m is even. We also determine the number of components in the case g = 1. Moreover we prove that any connected component is homeomorphic to a quotient of  $\mathbb{R}^d$  by a discrete group action.

The main technical tool is the following: We assign (Theorem 5.9) to a hyperbolic GQHSS of level m with corresponding Fuchsian group  $\Gamma$  a unique function on the space of homotopy classes of simple contours on the orbifold  $P = \mathbb{H}/\Gamma$  with values in  $\mathbb{Z}/m\mathbb{Z}$ , the associated m-Arf function.

The m-Arf functions are described by simple geometric properties:

**Definition:** Let P be a Riemann orbifold and  $p \in P$ . We denote by  $\pi^0(P, p)$  the set of all non-trivial elements of the orbifold fundamental group  $\pi(P, p)$  that can

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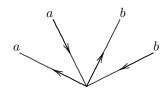


Figure 1:  $\hat{\sigma}(ab) = \hat{\sigma}(a) + \hat{\sigma}(b) - 1$ 

be represented by simple contours. An m-Arf function is a function

$$\sigma: \pi^0(P, p) \to \mathbb{Z}/m\mathbb{Z}$$

satisfying the following conditions

- 1.  $\sigma(bab^{-1}) = \sigma(a)$  for any elements  $a, b \in \pi^0(P, p)$ ,
- 2.  $\sigma(a^{-1}) = -\sigma(a)$  for any element  $a \in \pi^0(P, p)$  that is not of order 2,
- 3.  $\sigma(ab) = \sigma(a) + \sigma(b)$  for any elements a and b which can be represented by a pair of simple contours in P intersecting in exactly one point p with  $\langle a, b \rangle \neq 0$ ,
- 4.  $\sigma(ab) = \sigma(a) + \sigma(b) 1$  for any elements  $a, b \in \pi^0(P, p)$  such that the element ab is in  $\pi^0(P, p)$  and the elements a and b can be represented by a pair of simple contours in P intersecting in exactly one point p with  $\langle a, b \rangle = 0$  and placed in a neighbourhood of the point p as shown in Figure 1.
- 5. For any elliptic element c of order p we have  $p \cdot \sigma(c) + 1 \equiv 0 \mod m$ .

In order to be able to state our main results we need to give some definitions and notation.

**Definition:** Let  $\Gamma$  be a Fuchsian group of signature  $(g:p_1,\ldots,p_r)$  and let  $P=\mathbb{H}/\Gamma$  be the corresponding orbifold. Let  $\sigma:\pi^0(P,p)\to\mathbb{Z}/m\mathbb{Z}$  be an m-Arf function. We define the Arf invariant  $\delta=\delta(P,\sigma)$  of  $\sigma$  as follows: If g>1 and m is even then we set  $\delta=0$  if there is a standard basis  $\{a_1,b_1,\ldots,a_g,b_g,c_{g+1},\ldots,c_n\}$  of the fundamental group  $\pi(P,p)$  such that

$$\sum_{i=1}^{g} (1 - \sigma(a_i))(1 - \sigma(b_i)) \equiv 0 \mod 2$$

and we set  $\delta=1$  otherwise. If g>1 and m is odd then we set  $\delta=0$ . If g=0 then we set  $\delta=0$ . If g=1 then we set

$$\delta = \gcd(m, p_1 - 1, \dots, p_r - 1, \sigma(a_1), \sigma(b_1)),$$

where  $\{a_1, b_1, c_2, \ldots, c_{r+1}\}$  is a standard basis of the fundamental group  $\pi(P, p)$ . The type of the m-Arf function  $(P, \sigma)$  is the tuple  $(g, p_1, \ldots, p_r, \delta)$ , where  $\delta$  is the Arf invariant of  $\sigma$  defined above.

**Definition:** We denote by  $S^m(t) = S^m(g, p_1, \ldots, p_r, \delta)$  the set of all GQHSS of level m and signature  $(g: p_1, \ldots, p_r)$  such that the associated m-Arf function is of type  $t = (g, p_1, \ldots, p_r, \delta)$ .

The following Theorem summarizes the main results:

### Theorem:

1) Two hyperbolic GQHSS are in the same connected component of the space of all hyperbolic GQHSS if and only if they are of the same type. In other words,

the connected components of the space of all hyperbolic GQHSS are those sets  $S^{m}(t)$  that are not empty.

- 2) The set  $S^m(t)$  is not empty if and only if  $t = (g, p_1, \dots, p_r, \delta)$  has the following properties:
  - (a) The orders  $p_1, \ldots, p_r$  are prime with m and satisfy the condition

$$(p_1 \cdots p_r) \cdot \left( \sum_{i=1}^r \frac{1}{p_i} - (2g-2) - r \right) \equiv 0 \operatorname{mod} m.$$

- (b) If g > 1 and m is odd then  $\delta = 0$ .
- (c) If g = 1 then  $\delta$  is a divisor of  $gcd(m, p_1 1, \dots, p_r 1)$ .
- (d) If q = 0 then  $\delta = 0$ .
- 3) Any connected component  $S^m(t)$  of the space of all hyperbolic GQHSS of level m and signature  $(g:p_1,\ldots,p_r)$  is homeomorphic to a quotient of the space  $\mathbb{R}^{6g-6+2r}$  by a discrete action of a certain subgroup of the modular group (see section 6.3 for details).

The paper is organised as follows: In section 2 we explore the connection between hyperbolic GQHSS, roots of tangent bundles of orbifolds and lifts of Fuchsian groups into the coverings  $G_m$  of  $G = PSL(2, \mathbb{R})$ . In section 3 we study algebraic properties of the covering groups  $G_m$ . We describe a level function induced by a decomposition of the covering  $G_m$  into sheets and choosing a numeration of the sheets and study properties of these functions. In section 4 we study lifts of Fuchsian groups into  $G_m$ . In section 5 we define m-Arf functions. We prove that there is a 1-1-correspondence between the set of m-Arf functions and the set of functions associated to the lifts of Fuchsian groups into  $G_m$  via the numeration of the covering sheets. Hence these two sets are also in 1-1-correspondence with the set of all hyperbolic GQHSS of level m for a fixed orbifold. Moreover we show in this section using the explicit description of the generalised Dehn generators of the group of homotopy classes of surface autohomeomorphisms that the set of all m-Arf functions on an orbifold has a structure of an affine space. In the last section we find topological invariants of m-Arf functions and prove that they describe the connected components of the moduli space. Furthermore we show using a version of Theorem of Fricke and Klein [Nat78], [Zie81] that any connected component is homeomorphic to a quotient of  $\mathbb{R}^d$  by a discrete group action.

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## 2. Gorenstein singularities and lifts of Fuchsian groups

2.1. **Singularities and automorphy factors.** In this section we recall the results of Dolgachev, Milnor, Neumann and Pinkham [Dol75, Dol77, Mil75, Neu77, Pin77] on the graded affine coordinate rings, which correspond to quasi-homogeneous surface singularities.

**Definition 2.1.** A (negative unramified) automorphy factor  $(U, \Gamma, L)$  is a complex line bundle L over a simply connected Riemann surface U together with a discrete

co-compact subgroup  $\Gamma \subset \operatorname{Aut}(U)$  acting compatibly on U and on the line bundle L, such that the following two conditions are satisfied:

- 1) The action of  $\Gamma$  is free on  $L^*$ , the complement of the zero-section in L.
- 2) Let  $\tilde{\Gamma} \triangleleft \Gamma$  be a normal subgroup of finite index, which acts freely on U, and let  $E \rightarrow P$  be the complex line bundle  $E = L/\tilde{\Gamma}$  over the compact Riemann surface  $P = U/\tilde{\Gamma}$ . Then E is a negative line bundle, i.e. the self-intersection number  $E \cdot E$  is negative.

A simply connected Riemann surface U can be  $\mathbb{C}P^1$ ,  $\mathbb{C}$ , or  $\mathbb{H}$ , the real hyperbolic plane. We call the corresponding automorphy factor and the corresponding singularity *spherical*, *Euclidean*, resp. *hyperbolic*.

Remark. There always exists a normal freely acting subgroup of  $\Gamma$  of finite index [Dol83b]. In the hyperbolic case the existence follows from the theorem of Fox-Bundgaard-Nielsen. If the second assumption in the last definition holds for some normal freely acting subgroup of finite index, then it holds for any such subgroup, see [Dol83b].

The simplest examples of such complex line bundles with group actions are the cotangent bundle of the complex projective line  $U = \mathbb{C} \operatorname{P}^1$  and the tangent bundle of the hyperbolic plane  $U = \mathbb{H}$  equipped with the canonical action of a subgroup  $\Gamma \subset \operatorname{Aut}(U)$ .

Let  $(U, \Gamma, L)$  be a negative unramified automorphy factor. Since the bundle  $E = L/\tilde{\Gamma}$  is negative, one can contract the zero section of E to get a complex surface with one isolated singularity corresponding to the zero section. There is a canonical action of the group  $\Gamma/\tilde{\Gamma}$  on this surface. The quotient is a complex surface  $X(U, \Gamma, L)$  with an isolated singular point  $o(U, \Gamma, L)$ , which depends only on the automorphy factor  $(U, \Gamma, L)$ .

The following theorem summarizes the results of Dolgachev, Milnor, Neumann, and Pinkham:

**Theorem 2.1.** The surface  $X(U,\Gamma,L)$  associated to a negative unramified automorphy factor  $(U,\Gamma,L)$  is a quasi-homogeneous affine algebraic surface with a normal isolated singularity. Its affine coordinate ring is the graded  $\mathbb{C}$ -algebra of generalised  $\Gamma$ -invariant automorphic forms

$$A = \bigoplus_{m \geqslant 0} H^0(U, L^{-m})^{\Gamma}.$$

All normal isolated quasi-homogeneous surface singularities (X, x) are obtained in this way, and the automorphy factors with  $(X(U, \Gamma, L), o(U, \Gamma, L))$  isomorphic to (X, x) are uniquely determined by (X, x) up to isomorphism.

We now recall the definition of Gorenstein singularities and the characterization of the corresponding automorphy factors.

A normal isolated singularity of dimension n is Gorenstein if and only if there is a nowhere vanishing n-form on a punctured neighbourhood of the singular point. For example all isolated singularities of complete intersections are Gorenstein.

In [Dol83b] Dolgachev proved the following theorem obtained independently by W. Neumann (see also [Dol83a]).

**Theorem 2.2.** A quasi-homogeneous surface singularity is Gorenstein if and only if for the corresponding automorphy factor  $(U, \Gamma, L)$  there is an integer m (called the level or the exponent of the automorphy factor) such that the m-th tensor power  $L^m$  is  $\Gamma$ -equivariantly isomorphic to the tangent bundle  $T_U$  of the surface U.

Let  $(U, \Gamma, L)$  be an automorphy factor of level m, which corresponds to a Gorenstein singularity. The isomorphism  $L^m \cong T_U$  induces an isomorphism  $E^m \cong T_P$ . A simple computation with Chern numbers shows that the possible values of the exponent are m = -1 or m = -2 for  $U = \mathbb{C} P^1$ , whereas m = 0 for  $U = \mathbb{C}$  and m is a positive integer for  $U = \mathbb{H}$ .

2.2. Hyperbolic automorphy factors and lifts of Fuchsian groups. We consider the universal cover  $\widetilde{G} = \widetilde{\mathrm{PSL}}(2,\mathbb{R})$  of the Lie group

$$G = PSL(2, \mathbb{R}) = SL(2, \mathbb{R})/\{\pm 1\},$$

the group of orientation-preserving isometries of the hyperbolic plane. Here our model of the hyperbolic plane is the upper half-plane  $\mathbb{H}=\{z\in\mathbb{C}\mid \mathrm{Im}(z)>0\}$  and the action of an element  $[\binom{a\,b}{c\,d}]\in\mathrm{PSL}(2,\mathbb{R})$  on  $\mathbb{H}$  is by

$$z \mapsto \frac{az+b}{cz+d}.$$

We denote by  $[A] = [\binom{a \ b}{c \ d}] \in \mathrm{PSL}(2, \mathbb{R})$  the equivalence class of a matrix  $A = \binom{a \ b}{c \ d} \in \mathrm{SL}(2, \mathbb{R})$ .

As topological space  $G = \operatorname{PSL}(2, \mathbb{R})$  is homeomorphic to the open solid torus  $\mathbb{S}^1 \times \mathbb{C}$ . The fundamental group of the open solid torus G is infinite cyclic. Therefore, for each natural number m there is a unique connected m-fold covering

$$G_m = \tilde{G}/(m \cdot Z(\tilde{G}))$$

of G, where  $\tilde{G}$  is the universal covering of G and  $Z(\tilde{G})$  is the centre of  $\tilde{G}$ . For m=2 this is the group  $G_2=\mathrm{SL}(2,\mathbb{R})$ .

Here is another description of the covering groups  $G_m$  of G which fixes a group structure. Let  $\operatorname{Hol}(\mathbb{H},\mathbb{C}^*)$  be the set of all holomorphic functions  $\mathbb{H} \to \mathbb{C}^*$ .

**Proposition 2.3.** The m-fold covering group  $G_m$  of G can be described as

$$\{(g,\delta)\in G\times \operatorname{Hol}(\mathbb{H},\mathbb{C}^*)\mid \delta^m(z)=g'(z) \text{ for all } z\in\mathbb{H}\}$$

with multiplication  $(g_2, \delta_2) \cdot (g_1, \delta_1) = (g_2 \cdot g_1, (\delta_2 \circ g_1) \cdot \delta_1).$ 

*Proof.* Let X be the subspace of  $G \times \operatorname{Hol}(\mathbb{H}, \mathbb{C}^*)$  in question. One can check that the space X is connected and that the map  $X \to G$  given by  $(\gamma, \delta) \mapsto \gamma$  is an m-fold covering of G. Hence the coverings  $X \to G$  and  $G_m \to G$  are isomorphic. One can check that the operation described above defines a group structure on X and that the covering map  $X \to G$  is a homomorphism with respect to this group structure.

Remark. This description of  $G_m$  is inspired by the notion of automorphic differential forms of fractional degree, introduced by J. Milnor in [Mil75]. For a more detailed discussion of this fact see [LV80], section 1.8.

A Fuchsian group  $\Gamma \subset \mathrm{PSL}(2,\mathbb{R})$  acts on the hyperbolic plane  $\mathbb{H}$ . A hyperbolic Gorenstein automorphy factor of level m (associated to the Fuchsian group  $\Gamma$ ) is an action of a Fuchsian group  $\Gamma$  on the trivial complex line bundle  $\mathbb{H} \times \mathbb{C}$  over the hyperbolic plane  $\mathbb{H}$  given by

$$g \cdot (z, t) = (g(z), \delta_g(z) \cdot t),$$

where  $\delta_g : \mathbb{H} \to \mathbb{C}^*$  is a holomorphic function, for any  $g \in \Gamma$  we have  $\delta_g^m = g'$  and for any  $g_1, g_2 \in \Gamma$  we have  $\delta_{g_2 \cdot g_1} = (\delta_{g_2} \circ g_1) \cdot \delta_{g_1}$ .

**Definition 2.2.** A *lift* of the Fuchsian group  $\Gamma$  into  $G_m$  is a subgroup  $\Gamma^*$  of  $G_m$  such that the restriction of the covering map  $G_m \to G$  to  $\Gamma^*$  is an isomorphism between  $\Gamma^*$  and  $\Gamma$ .

Using the description of the m-fold covering group  $G_m$  of G in Proposition 2.3 we obtain the following result:

**Proposition 2.4.** There is a 1-1-correspondence between the lifts of  $\Gamma$  into  $G_m$  and hyperbolic Gorenstein automorphy factors of level m associated to the Fuchsian group  $\Gamma$ .

- 3. Level functions on covering groups of  $PSL(2,\mathbb{R})$
- 3.1. Classification of elements in the covering groups of  $G = PSL(2, \mathbb{R})$ . Elements of G can be classified with respect to the fixed point behavior of their action on H. An element is called hyperbolic if it has two fixed points, which lie on the boundary  $\partial \mathbb{H} = \mathbb{R} \cup \{\infty\}$  of  $\mathbb{H}$ . One of the fixed points of a hyperbolic element is attracting, the other fixed point is repelling. The axis  $\ell(g)$  of a hyperbolic element g is the geodesic between the fixed points of g, oriented from the repelling fixed point to the attracting fixed point. The element g preserves the geodesic  $\ell(g)$ . We call a hyperbolic element with attracting fixed point  $\alpha$  and repelling fixed point  $\beta$  positive if  $\alpha < \beta$ . The shift parameter of a hyperbolic element g is the minimal displacement  $\inf_{x\in\mathbb{H}} d(x,g(x))$ . An element is called *parabolic* if it has one fixed point, which is on the boundary  $\partial \mathbb{H}$ . We call a parabolic element g with fixed point  $\alpha$  positive if g(x) > x for all  $x \in \mathbb{R} \setminus \{\alpha\}$ . An element that is neither hyperbolic nor parabolic is called *elliptic*. It has one fixed point that is in  $\mathbb{H}$ . Given a base-point  $x \in \mathbb{H}$  and a real number  $\varphi$ , let  $\rho_x(\varphi) \in G$  denote the rotation through angle  $\varphi$  counter-clockwise about the point x. Any elliptic element is of the form  $\rho_x(\varphi)$ , where x is the fixed point. Thus we obtain a  $2\pi$ -periodic homomorphism  $\rho_x:\mathbb{R}\to G$  (with respect to the additive structure on  $\mathbb{R}$ ). Elements of  $\tilde{G}$  resp.  $G_m$ can be classified with respect to the fixed point behavior of action on H of their image in G. We say that an element of  $\tilde{G}$  resp.  $G_m$  is hyperbolic, parabolic resp. *elliptic* if its image in G has this property.
- 3.2. Central elements in covering groups of  $G = \operatorname{PSL}(2,\mathbb{R})$ . The homomorphism  $\rho_x : \mathbb{R} \to G$  lifts to a unique homomorphism  $r_x : \mathbb{R} \to \tilde{G}$  into the universal covering group. Since  $\rho_x(2\pi\ell) = \operatorname{id}$  for  $\ell \in \mathbb{Z}$ , it follows that the lifted element  $r_x(2\pi\ell)$  belongs to the centre  $Z(\tilde{G})$  of  $\tilde{G}$ . Note that the element  $r_x(2\pi\ell)$  depends continuously on x. But the centre of  $\tilde{G}$  is discrete, so this element must remain constant, thus  $r_x(2\pi\ell)$  does not depend on x. The centre  $Z(\tilde{G})$  of  $\tilde{G}$  is equal to the pre-image of the identity element under the projection  $\tilde{G} \to G$ , hence  $Z(\tilde{G}) = \{r_x(2\pi\ell) \mid \ell \in \mathbb{Z}\}$ . Let  $u = r_x(2\pi)$  for some (and hence for any) x in  $\mathbb{H}$ .

The element u is one of the two generators of the centre of  $\tilde{G}$  since any other element of the centre is of the form  $r_x(2\pi\ell) = (r_x(2\pi))^\ell = u^\ell$ . We would also like to point out that for the lift of an elliptic element  $\rho_x(2\pi/p)$  of finite order p we have  $(r_x(2\pi/p))^p = r_x(2\pi) = u$ .

3.3. **Definition of a level function.** Let  $\Delta$  be the set of all elliptic elements of order 2 in G. Let  $\Xi$  be the complement in G of the set  $\Delta$ . The space G is homeomorphic to the open solid torus  $\mathbb{S}^1 \times \mathbb{C}$ . In [JN85] Jankins and Neumann give an explicit homeomorphism (see [JN85], Apendix). The image of the set  $\Delta$  under this homeomorphism is  $\{*\} \times \mathbb{C}$ . From this description it follows in particular that the subset  $\Xi$  is simply connected. The pre-image  $\tilde{\Xi}$  of the subset  $\Xi$  in  $\tilde{G}$  consists of infinitely many connected components. Each connected component of the subset  $\tilde{\Xi}$  contains one and only one pre-image of the identity element of G, i.e. one and only one element of the centre of  $\tilde{G}$ .

**Definition 3.1.** If an element of G is contained in the same connected component of the set  $\Xi$  as the central element  $u^k$ ,  $k \in \mathbb{Z}$ , we say that the element is at the level k and set the level function s on this element to be equal to k. For pre-images of elliptic elements of order 2 we set  $s(r_x(\xi)) = k$  for  $\xi = \pi + 2\pi k$ .

Remark. For elliptic elements we have  $s(r_x(\xi)) = k \iff \xi \in (-\pi + 2\pi k, \pi + 2\pi k]$ .

**Definition 3.2.** We define the level function  $s_m$  on elements of  $G_m = \tilde{G}/(m \cdot Z(\tilde{G}))$  by  $s_m(g \mod (m \cdot Z(\tilde{G}))) = s(g) \mod m$  for  $g \in \tilde{G}$ . (All equations involving  $s_m$  are to be understood as equations in  $\mathbb{Z}/m\mathbb{Z}$ , i.e. equations modulo m.)

**Definition 3.3.** The canonical lift of an element  $\bar{C}$  in G into  $\tilde{G}$  is an element  $\tilde{C}$  in  $\tilde{G}$  such that  $\pi(\tilde{C}) = \bar{C}$  and  $s(\tilde{C}) = 0$ . The canonical lift of an element  $\bar{C}$  in G into  $G_m$  is an element  $\tilde{C}$  in  $G_m$  such that  $\pi(\tilde{C}) = \bar{C}$  and  $s_m(\tilde{C}) = 0$ .

3.4. Properties of the level function. In this subsection we study the behavior of the level function  $s_m$  under inversion (Lemma 3.1), conjugation (Lemma 3.2) and multiplication in some special cases (Lemma 3.3). We shall obtain further statements about the behavior of the level function under multiplication in Corollary 4.7.

In this section we shall repeatedly use the following fact: Connected components of the set  $\tilde{\Xi}$  are separated from each other by connected components of the set  $\tilde{\Delta}$  of all pre-images of (elliptic) elements of order 2. If a path  $\gamma$  in  $\tilde{G}$  avoids all pre-images of elements of order 2, i.e. avoids  $\tilde{\Delta}$ , then it means that the path  $\gamma$  remains in the same component of the set  $\tilde{\Xi}$  and therefore the level function s is constant along  $\gamma$ .

**Lemma 3.1.** The equation  $s(A^{-1}) = -s(A)$  is satisfied for any element A in  $\tilde{G}$  with exception of pre-images of elliptic elements of order 2. The equation  $s_m(A^{-1}) = -s_m(A)$  is satisfied for any element A in  $G_m$  with exception of pre-images of elliptic elements of order 2.

Proof. We shall prove the statement about the level function s on  $\tilde{G}$ , the statement about the level function  $s_m$  on  $G_m$  follows immediately. Let  $A \in G$  and let k = s(A), then A is in the same connected component of  $\tilde{\Xi}$  as  $u^k$ . Let  $\gamma$  be the path in  $\tilde{\Xi}$  that connects A with  $u^k$ . Let the path  $\delta$  be given by  $\delta(t) = (\gamma(t))^{-1}$ . The path  $\delta$  connects  $A^{-1}$  with  $u^{-k}$ . The path  $\gamma$  remains in the same component of  $\tilde{\Xi}$ , i.e. it avoids pre-images of elliptic elements of order 2. Consequently, the path  $\delta$  also

avoids pre-images of elements of order 2, i.e. it remains in the same component of  $\tilde{\Xi}$ . Thus the element  $A^{-1}$  is in the same connected component of  $\tilde{\Xi}$  as  $u^{-k}$ , i.e.  $s(A^{-1}) = -k = -s(A)$ .

**Lemma 3.2.** For any elements A and B in  $\tilde{G}$  we have  $s(BAB^{-1}) = s(A)$ . For any elements A and B in  $G_m$  we have  $s_m(BAB^{-1}) = s_m(A)$ .

Proof. We shall prove the statement about the level function s on  $\tilde{G}$ , the statement about the level function  $s_m$  on  $G_m$  follows immediately. The element B can be connected to the unit element in  $\tilde{G}$  via a path  $\beta: I \to \tilde{G}$ , where I is some closed interval. The path  $\gamma: I \to \tilde{G}$  given by  $\gamma(t) = \beta(t) \cdot A \cdot (\beta(t))^{-1}$  connects the elements A and  $B \cdot A \cdot B^{-1}$ . If A is not in  $\tilde{\Delta}$  then the same is true for the conjugate  $\gamma(t)$  of A, hence the path  $\gamma$  remains in the same component of the set  $\tilde{\Xi}$ . Thus s is constant along  $\gamma$ , in particular  $s(B \cdot A \cdot B^{-1}) = s(A)$ . If A is in  $\tilde{\Delta}$  then the conjugate  $\gamma(t)$  of A is also in  $\tilde{\Delta}$ , hence the path  $\gamma$  remains in the same component of the set  $\tilde{\Delta}$ . Thus s is constant along  $\gamma$ , in particular  $s(B \cdot A \cdot B^{-1}) = s(A)$ .  $\square$ 

**Lemma 3.3.** If the axes of two hyperbolic elements A and B in  $\tilde{G}$  intersect then s(AB) = s(A) + s(B). If the axes of two hyperbolic elements A and B in  $G_m$  intersect then  $s_m(AB) = s_m(A) + s_m(B)$ .

Proof. Let  $\ell_A$  resp.  $\ell_B$  be the axes of A resp. B. Let x be the intersection point of  $\ell_A$  and  $\ell_B$ . Any hyperbolic transformation with the axis  $\ell_A$  is a product of a rotation by  $\pi$  at some point  $y \neq x$  on  $\ell_A$  and a rotation by  $\pi$  at the point x. Similarly any hyperbolic transformation with the axis  $\ell_B$  is a product of a rotation by  $\pi$  at the point x and a rotation by  $\pi$  at some point  $z \neq x$  on  $\ell_B$ . Hence the product of any hyperbolic transformation with the axis  $\ell_A$  and any hyperbolic transformation with the axis  $\ell_B$  is a product of a rotation by  $\pi$  at a point  $y \neq x$  on  $\ell_A$  and a rotation by  $\pi$  at a point  $z \neq x$  on  $\ell_B$ , i.e. it is a hyperbolic transformation with an axis going through the points y and z. Thus the product of two hyperbolic elements with distinct but intersecting axes is always a hyperbolic element.

We shall prove the statement about the level function s on  $\tilde{G}$ , the statement about the level function  $s_m$  on  $G_m$  follows immediately. Assume without loss of generality that the elements  $A, B \in \tilde{G}$  satisfy the conditions s(A) = s(B) = 0. We want to show that s(AB) = 0. Let us deform the elements A and B. We shall not change the axes but decrease the shift parameters, then the product tends to the identity element. On the other hand we have explained that the product remains hyperbolic, i.e. stays in  $\tilde{\Xi}$ . Therefore the value of s on the product remains constant, i.e.  $s(AB) = s(\mathrm{id}) = 0$ .

### 4. Level functions on lifts of Fuchsian groups

### 4.1. Lifting elliptic cyclic subgroups.

**Lemma 4.1.** Let  $\Gamma$  be an elliptic cyclic Fuchsian group of order p.

1) Let us assume that the numbers p and m are relatively prime. Then the lift  $\Gamma^*$  of  $\Gamma$  into  $G_m$  exists and is unique. There is a unique element  $n \in \mathbb{Z}/m\mathbb{Z}$  such that  $p \cdot n + 1 = 0 \mod m$ . The lift  $\Gamma^*$  is then determined by the following property: If the elliptic element  $\gamma = \rho_x(2\pi/p)$  is a generator of the group  $\Gamma$ , then the lift  $\Gamma^*$  is generated by the pre-image  $\tilde{\gamma}$  of  $\gamma$  in  $G_m$  such that  $s_m(\tilde{\gamma}) = n$ .

2) Let us assume that the numbers a and m are not relatively prime. Then the group  $\Gamma$  can not be lifted into  $G_m$ .

Proof. Let  $\gamma = \rho_x(2\pi/p)$  be a generator of the group  $\Gamma$ . To lift  $\Gamma$  into  $G_m$  we have to find an element  $\tilde{\gamma}$  in the pre-image of  $\gamma$  in  $G_m$  such that  $\tilde{\gamma}^p = 1$ . The pre-image of  $\gamma$  in  $G_m$  can be described as the coset  $\{u^n \cdot r_x(2\pi/p) \mid n \in \mathbb{Z}/m\mathbb{Z}\}$ . For the element  $r_x(2\pi/p)$  we obtain  $(r_x(2\pi/p))^p = r_x(2\pi) = u$ . Hence for an element  $u^n \cdot r_x(2\pi/p)$  we obtain

$$(u^n \cdot r_x(2\pi/p))^p = u^{np}(r_x(2\pi/p))^p = u^{np+1}.$$

Therefore  $(u^n \cdot r_x(2\pi/p))^p = 1$  if and only if  $n \cdot p + 1 = 0 \mod m$ . There exists  $n \in \mathbb{Z}/m\mathbb{Z}$  with  $n \cdot p + 1 = 0 \mod m$  if and only if the numbers p and m are relatively prime. Hence for not relatively prime p and m it is impossible to lift  $\Gamma$  into  $G_m$ . For relatively prime p and m there is a unique lift of  $\Gamma$  into  $G_m$  generated by  $u^n \cdot r_x(2\pi/p)$  with  $s_m(u^n \cdot r_x(2\pi/p)) = n$  and  $n \cdot p + 1 = 0 \mod m$ .

4.2. Finitely generated Fuchsian groups. In this section we are going to describe finitely generated (co-compact) Fuchsian groups using standard sets of generators. The following definitions follow [Zie81]:

**Definition 4.1.** A Riemann factor surface or Riemann orbifold (P,Q) of signature

$$(g; l_h, l_p, l_e : p_1, \dots, p_{l_e})$$

is a topological surface P of genus g with  $l_h$  holes and  $l_p$  punctures and a set  $Q = \{(x_1, p_1), \ldots, (x_{l_e}, p_{l_e})\}$  of points  $x_i$  in P equipped with orders  $p_i$  such that  $p_i \in \mathbb{Z}$ ,  $p_i \geq 2$  and  $x_i \neq x_j$  for  $i \neq j$ . The set Q is called the *marking* of the Riemann factor surface (P, Q).

**Definition 4.2.** Let  $(P, Q = \{(x_1, p_1), \dots, (x_{l_e}, p_{l_e})\})$  be a Riemann factor surface. Two curves  $\gamma_0$  and  $\gamma_1$  which do not pass through exceptional points  $x_i \in Q$  are called Q-homotopic if  $\gamma_0$  can be deformed into  $\gamma_1$  by a finite sequence of the following processes:

- (a) Homotopic deformations with fixed starting point such that during the deformation no exceptional point is encountered.
- (b) Omitting a subcurve of  $\gamma_i$  which does not contain the starting point of  $\gamma_i$  and is of the form  $\delta^{\pm p_i}$ , where  $\delta$  is a curve on P which bounds a disk that contains exactly one exceptional point  $x_i$  in the interior.
- (c) Inserting into  $\gamma_i$  a subcurve which does not contain the starting point of  $\gamma_i$  and is of the form  $\delta^{\pm p_i}$ , where  $\delta$  is a curve on P which bounds a disk that contains exactly one exceptional point  $x_i$  in the interior.

Two curves  $\gamma_0$  and  $\gamma_1$  which do not pass through exceptional points  $x_i \in Q$  are called *freely Q-homotopic* if the base point may be moved during the deformations.

**Definition 4.3.** Let  $(P, Q = \{(x_1, p_1), \dots, (x_{l_e}, p_{l_e})\})$  be a Riemann factor surface and  $p \in P \setminus Q$ . Then the set of Q-homotopy classes of curves starting and ending in p forms a group. This group is called the Q-fundamental group or the orbifold fundamental group and denoted by  $\pi^Q(P, p)$  or  $\pi(P, p)$ .

**Definition 4.4.** Let  $\Gamma$  be a Fuchsian group. The quotient  $P = \mathbb{H}/\Gamma$  is a surface and the projection  $\Psi : \mathbb{H} \to P$  is a branched cover. Let Q consist of the branching points and the corresponding orders. Then (P,Q) is a factor surface. We say that the factor surface (P,Q) is defined by  $\Gamma$ .

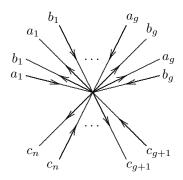


Figure 2: Canonical system of curves

**Proposition 4.2.** Let  $\Gamma$  be a Fuchsian group, (P,Q) the corresponding factor surface and  $p \in P \setminus Q$ . Then  $\pi(P,p) \cong \Gamma$ .

**Definition 4.5.** A canonical system of curves on a Riemann factor surface  $(P, Q = \{(x_1, p_1), \ldots, (x_{l_e}, p_{l_e})\})$  of signature  $(g; l_h, l_p, l_e : p_1, \ldots, p_{l_e})$  is a set of simply closed curves based at a point  $p \in P$ 

$$\{\tilde{a}_1, \tilde{b}_1, \dots, \tilde{a}_g, \tilde{b}_g, \tilde{c}_{g+1}, \dots, \tilde{c}_{g+l_h+l_p+l_e}\},$$

where  $n = g + l_h + l_p + l_e$ , with the following properties:

- 1) The contour  $\tilde{c}_i$  encloses a hole in P for  $i = g + 1, \ldots, g + l_h$ , a puncture for  $i = g + l_h + 1, \ldots, g + l_h + l_p$  and the marking point  $x_i$  for  $i = g + l_h + l_p + 1, \ldots, n$ .
- 2) Any two curves only intersect at the point p.
- 3) In a neighbourhood of the point p, the curves are placed as is shown in Figure 2.
- 4) The system of curves cuts the surface P into  $l_h + l_p + l_e + 1$  connected components of which  $l_p + l_e$  are homeomorphic to a disc with a hole,  $l_h + 1$  are discs. The last disc has boundary

$$\tilde{a}_1\tilde{b}_1\tilde{a}_1^{-1}\tilde{b}_1^{-1}\dots\tilde{a}_g\tilde{b}_g\tilde{a}_q^{-1}\tilde{b}_q^{-1}\tilde{c}_g\dots\tilde{c}_n.$$

If  $\{\tilde{a}_1, \tilde{b}_1, \dots, \tilde{a}_g, \tilde{b}_g, \tilde{c}_{g+1}, \dots, \tilde{c}_{g+l_h+l_p+l_e}\}$  is a canonical system of curves, then we call the corresponding set  $\{a_1, b_1, \dots, a_g, b_g, c_{g+1}, \dots, c_{g+l_h+l_p+l_e}\}$  of elements in the orbifold fundamental group  $\pi(P, p)$  a standard basis or a standard set of generators of  $\pi(P, p)$ .

**Definition 4.6.** A sequential set of signature  $(0; l_h, l_p, l_e : p_1, \ldots, p_{l_e})$  with  $l_h + l_p + l_e = 3$  is a triple of elements  $(C_1, C_2, C_3)$  in G such that the element  $C_i$  is hyperbolic for  $i = 1, \ldots, l_h$ , parabolic for  $i = l_h + 1, \ldots, l_h + l_p$  and elliptic of order  $p_{i-l_h-l_p}$  for  $i = l_h + l_p + 1, \ldots, l_h + l_p + l_e = 3$ , their product is  $C_1 \cdot C_2 \cdot C_3 = 1$ , and for some element  $A \in G$  the elements  $\{\tilde{C}_i = AC_iA^{-1}\}_{i=1,2,3}$  are positive, have finite fixed points and satisfy  $\tilde{C}_1 < \tilde{C}_2 < \tilde{C}_3$ . (Figure 3 illustrates the position of the axes of the elements  $\tilde{C}_i$  for a sequential set of signature (0,3,0), i.e. when all elements are hyperbolic.)

**Definition 4.7.** A sequential set of signature  $(0; l_h, l_p, l_e : p_1, \ldots, p_{l_e})$  is a tuple of elements  $(C_1, \ldots, C_{l_h + l_p + l_e})$  in G such that the element  $C_i$  is hyperbolic for  $i = 1, \ldots, l_h$ , parabolic for  $i = l_h + 1, \ldots, l_h + l_p$  and elliptic of order  $p_{i-l_h - l_p}$ 

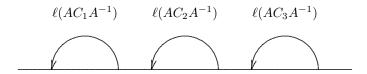


Figure 3: Axes of a sequential set of signature (0; 3, 0, 0)

for  $i = l_h + l_p + 1, \ldots, l_h + l_p + l_e$ , and for any  $i \in \{2, \ldots, n-1\}$  the triple  $(C_1 \cdots C_{i-1}, C_i, C_{i+1} \cdots C_n)$  is a sequential set.

**Definition 4.8.** A sequential set of signature  $(g; l_h, l_p, l_e : p_1, \ldots, p_{l_e})$  is a tuple of elements

$$(A_1,\ldots,A_q,B_1,\ldots,B_q,C_{q+1},\ldots,C_{q+l_h+l_n+l_e})$$

in G such that the elements  $A_1,\ldots,A_g,B_1,\ldots,B_g$  are hyperbolic, the element  $C_{g+i}$  is hyperbolic for  $i=1,\ldots,l_h$ , parabolic for  $i=l_h+1,\ldots,l_h+l_p$  and elliptic of order  $p_{i-l_h-l_p}$  for  $i=l_h+l_p+1,\ldots,l_h+l_p+l_e$ , and the tuple

$$(A_1, B_1 A_1^{-1} B_1^{-1}, \dots, A_g, B_g A_g^{-1} B_g^{-1}, C_{g+1}, \dots, C_{g+l_h+l_p+l_e})$$

is a sequential set of signature  $(0; 2g + l_h, l_p, l_e : p_1, \dots, p_{l_e})$ .

The relation between sequential sets, standard bases, canonical systems of curves and Fuchsian groups was studied in [Nat72]. Details for the case of Fuchsian groups with elliptic elements can be found in [Zie81]. We recall here the results:

**Theorem 4.3.** Let V be a sequential set of signature  $(g; l_h, l_p, l_e : p_1, \ldots, p_{l_e})$ . For  $i = 1, \ldots, l_e$  let  $y_i \in \mathbb{H}$  be the fixed point of the corresponding elliptic element of order  $p_i$  in V. Let  $P = \mathbb{H}/\Gamma$  and let  $\Psi : \mathbb{H} \to P$  be the natural projection. Let  $Q = \{(\Psi(y_1), p_1), \ldots, (\Psi(y_{l_e}), p_{l_e})\}$ . Then the sequential set V generates a Fuchsian group  $\Gamma$  such that the Riemann factor surface  $(P = \mathbb{H}/\Gamma, Q)$  is of signature  $(g; l_h, l_p, l_e : p_1, \ldots, p_{l_e})$ . The natural projection  $\Psi : \mathbb{H} \to P$  maps the sequential set V to a canonical system of curves on the factor surface (P, Q).

**Theorem 4.4.** Let  $\Gamma$  be a Fuchsian group such that the factor surface  $P = \mathbb{H}/\Gamma$  is of signature  $(g; l_h, l_p, l_e : p_1, \ldots, p_{l_e})$ . Let p be a point in P which does not belong to the marking. Let  $\Psi : \mathbb{H} \to P$  be the natural projection. Choose  $q \in \Psi^{-1}(p)$  and let  $\Phi : \Gamma \to \pi(P, p)$  be the induced isomorphism. Let

$$v = \{\tilde{a}_1, \tilde{b}_1, \dots, \tilde{a}_g, \tilde{b}_g, \tilde{c}_{g+1}, \dots, \tilde{c}_n\}$$

be a canonical system of curves on P. In this case,

$$V = \Phi^{-1}(v) = \{\Phi^{-1}(a_1), \Phi^{-1}(b_1), \dots, \Phi^{-1}(a_g), \Phi^{-1}(b_g), \Phi^{-1}(c_{g+1}), \dots, \Phi^{-1}(c_n)\}$$
$$= \{A_1, B_1, \dots, A_g, B_g, C_{g+1}, \dots, C_n\}$$

is a sequential set of signature  $(g; l_h, l_p, l_e : p_1, \ldots, p_{l_e})$ .

## 4.3. Lifting Fuchsian groups of genus 0.

**Lemma 4.5.** Let  $(0; l_h, l_p, l_e : p_1, \ldots, p_{l_e})$  with  $l_h + l_p + l_e = n$  be the signature of the sequential set  $(\bar{C}_1, \ldots, \bar{C}_n)$ . For  $i = 1, \ldots, n$  let  $\tilde{C}_i$  be the canonical lift of  $\bar{C}_i$  into  $\bar{G}$  or  $G_m$ . Let u be the generator of the centre  $Z(\bar{G})$  resp.  $Z(G_m)$ . The element u is given by the element  $r_x(\pi)$  resp. its projection into  $G_m$ . Then the elements  $\tilde{C}_1, \ldots, \tilde{C}_n$  satisfy the following relations:  $\tilde{C}_{l_h+l_p+i}^{p_i} = u$  for  $i = 1, \ldots, l_e$  and

$$\tilde{C}_1 \cdot \dots \cdot \tilde{C}_n = u^{n-2}$$
.

*Proof.* Let  $\Pi$  be the canonical fundamental polygon for the group generated by the elements  $\bar{C}_1, \ldots, \bar{C}_n$  such that the generators  $\bar{C}_i$  can be described as products

$$\bar{C}_i = \sigma_i \sigma_{i+1}$$

of reflexions  $\sigma_1, \ldots, \sigma_n$  in the edges of the polygon  $\Pi$  (suitably numbered). Then  $\sigma_i^2 = \mathrm{id}$ , and therefore

$$\bar{C}_1 \cdots \bar{C}_n = (\sigma_1 \sigma_2)(\sigma_2 \sigma_3) \cdots (\sigma_{n-1} \sigma_n)(\sigma_n \sigma_1) = \mathrm{id}.$$

Lifting the elements  $\bar{C}_i$  to their canonical lifts  $\tilde{C}_i$  in  $\tilde{G}$ , it follows that the product  $\tilde{C}_1 \cdots \tilde{C}_n$  belongs to the centre  $Z(\tilde{G})$ . As we vary the polygon  $\Pi$  continuously, this central element must also vary continuously. But  $Z(\tilde{G})$  is a discrete group, so  $\tilde{C}_1 \cdots \tilde{C}_n$  must remain constant. In particular we can shrink the polygon  $\Pi$  down towards a point x. In the course of this continuous deformation of the fundamental polygon  $\Pi$  the hyperbolic and parabolic elements of the sequential set will become elliptic. As we continue shrinking the polygon  $\Pi$  towards the point x, the angles of the polygon tend to the angles  $\beta_1, \ldots, \beta_n$  of some Euclidean n-sided polygon. Thus the element  $\tilde{C}_i \in \tilde{G}$  tends towards the limit  $r_x(2\beta_i)$ , while the product  $\tilde{C}_1 \cdots \tilde{C}_n$  tends towards the product

$$r_x(2\beta_1)\cdots r_x(2\beta_n) = r_x(2\beta_1 + \cdots + 2\beta_n).$$

Therefore, using the formula

$$\beta_1 + \dots + \beta_n = (n-2)\pi$$

for the sum of the angles of a Euclidean n-sided polygon, we see that the constant product  $\tilde{C}_1 \cdots \tilde{C}_n$  must be equal to

$$r_x(2(n-2)\pi) = u^{n-2}$$
.

Projecting into  $G_m$  we get the corresponding statement in  $G_m$ .

**Lemma 4.6.** Let  $(C_1, \ldots, C_n)$  be an n-tuple of elements in  $G_m$  such that their images  $(\bar{C}_1, \ldots, \bar{C}_n)$  in G form a sequential set of signature  $(0; l_h, l_p, l_e : p_1, \ldots, p_{l_e})$  with  $l_h + l_p + l_e = n$ . Then  $C_1 \cdots C_n = e$  if and only if

$$s_m(C_1) + \dots + s_m(C_n) = -(n-2).$$

*Proof.* For i = 1, ..., n let  $\tilde{C}_i$  be the canonical lift of  $\bar{C}_i$  into  $G_m$ . The elements  $C_i$  can be written in the form

$$C_i = \tilde{C}_i \cdot u^{s_m(C_i)},$$

therefore

$$C_1 \cdots C_n = (\tilde{C}_1 \cdot u^{s_m(C_1)}) \cdots (\tilde{C}_n \cdot u^{s_m(C_n)}) = (\tilde{C}_1 \cdots \tilde{C}_n) \cdot c^{s_m(C_1) + \dots + s_m(C_n)}.$$

According to Lemma 4.5 the product of the elements  $\tilde{C}_i$  is

$$\tilde{C}_1 \cdot \cdot \cdot \cdot \tilde{C}_n = u^{n-2}$$
,

hence

$$C_1 \cdots C_n = u^{n-2+s_m(C_1)+\cdots+s_m(C_n)}.$$

Therefore the product  $C_1 \cdots C_n$  is equal to e if and only if the exponent of u in the last equation is divisible by m, i.e. if

$$s_m(C_1) + \cdots + s_m(C_n) \equiv -(n-2) \mod m$$
.  $\square$ 

**Corollary 4.7.** Let  $(C_1, C_2, C_3)$  be an triple of elements in  $G_m$  with  $C_1C_2C_3 = e$ . Let  $\bar{C}_i$  be the image of the element  $C_i$  in G. Let  $(\bar{C}_1, \bar{C}_2, \bar{C}_3)$  be a sequential set of signature  $(0; l_h, l_p, l_e : p_1, \ldots, p_{l_e})$  with  $l_h + l_p + l_e = 3$ . Then

$$s_m(C_1 \cdot C_2) = s_m(C_1) + s_m(C_2) + 1$$

if the element  $C_3$  is not of order 2 and

$$s_m(C_1 \cdot C_2) = -s_m(C_1) - s_m(C_2) - 1$$

if the element  $C_3$  is of order 2.

*Proof.* According to Lemma 4.6 the elements  $C_i$  satisfy

$$s_m(C_1) + s_m(C_2) + s_m(C_3) \equiv -1 \mod m.$$

On the other hand  $C_1C_2C_3 = e$  implies  $C_1C_2 = C_3^{-1}$ , hence

$$s_m(C_1C_2) = s_m(C_3^{-1}) = -s_m(C_3) = s_m(C_1) + s_m(C_2) + 1$$

if the element  $C_3$  is not of order 2 and

$$s_m(C_1C_2) = s_m(C_3^{-1}) = s_m(C_3) = -s_m(C_1) - s_m(C_2) - 1$$

if the element  $C_3$  is of order 2.

## 4.4. Lifting sets of generators of Fuchsian groups.

**Lemma 4.8.** Let  $\Gamma$  be a Fuchsian group of signature  $(g; l_h, l_p, l_e : p_1, \ldots, p_{l_e})$  generated by the sequential set  $\bar{V} = \{\bar{A}_1, \bar{B}_1, \ldots, \bar{A}_g, \bar{B}_g, \bar{C}_{g+1}, \ldots, \bar{C}_n\}$ , where  $n = g + l_h + l_p + l_e$ . Let  $V = \{A_1, B_1, \ldots, A_g, B_g, C_{g+1}, \ldots, C_n\}$  be a set of lifts of the elements of the sequential set  $\bar{V}$  into  $G_m$ , i.e. the image of  $A_i$ ,  $B_i$  resp.  $C_j$  in G is  $\bar{A}_i$ ,  $\bar{B}_i$  resp.  $\bar{C}_j$ . Then the subgroup  $\Gamma^*$  of  $G_m$  generated by V is a lift of  $\Gamma$  into  $G_m$  if and only if

$$[A_1, B_1] \cdots [A_g, B_g] \cdot C_{g+1} \cdots C_n = e, \quad C_{g+l_h+l_n+i}^{p_i} = e \quad \text{for } i = 1, \dots, l_e.$$

*Proof.* For any choice of the set of lifts V the restriction of the covering map  $G_m \to G$  to the group  $\Gamma^*$  generated by V is a homomorphism with image  $\Gamma$ . If the conditions of the lemma hold true, then the group  $\Gamma^*$  satisfies the same relations as the group  $\Gamma$ , hence this homomorphism is injective.

## Lemma 4.9. Let

$$\{A_1, B_1, \dots, A_g, B_g, C_{g+1}, \dots, C_n\}$$

be a tuple of elements in  $G_m$  such that the images

$$\{\bar{A}_1, \bar{B}_1, \dots, \bar{A}_q, \bar{B}_q, \bar{C}_{q+1}, \dots, \bar{C}_n\}$$

in G form a sequential set of signature  $(g; l_h, l_p, l_e : p_1, \dots, p_{l_e})$  with  $g + l_h + l_p + l_e = n$ . Then

$$\prod_{i=1}^{g} [A_i, B_i] \cdot \prod_{j=g+1}^{n} C_j = e \iff \sum_{j=g+1}^{n} s_m(C_j) \equiv (2 - 2g) - (n - g) \mod m.$$

(in the case n = g this means  $2 - 2g \equiv 0 \mod m$ ) and for any  $i = 1, \ldots, l_e$ 

$$C_{g+l_h+l_p+i}^{p_i} = e \iff p_i \cdot s_m(C_{g+l_h+l_p+i}) + 1 \equiv 0 \bmod m.$$

*Proof.* The case g=0 was discussed in Lemma 4.6. We shall now reduce the general case to the case g=0. By definition of sequential sets the set

$$(\bar{A}_1, \bar{B}_1 \bar{A}_1^{-1} \bar{B}_1^{-1}, \dots, \bar{A}_g, \bar{B}_g \bar{A}_g^{-1} \bar{B}_g^{-1}, \bar{C}_{g+1}, \dots, \bar{C}_n)$$

is a sequential set of signature  $(0; 2g + l_h, l_p, l_e)$ , hence

$$\prod_{i=1}^{g} [A_i, B_i] \cdot \prod_{i=g+1}^{n} C_i = \prod_{i=1}^{g} (A_i \cdot B_i A_i^{-1} B_i^{-1}) \cdot \prod_{i=g+1}^{n} C_i = e$$

if and only if

$$\sum_{i=1}^{g} (s_m(A_i) + s_m(B_i A_i^{-1} B_i^{-1})) + \sum_{i=g+1}^{n} s_m(C_i) \equiv -(2g + (n-g) - 2)$$
$$\equiv (2 - 2g) - (n-g) \bmod m.$$

Invariance of the level function  $s_m$  under conjugation (Lemma 3.2) implies that

$$s_m(B_i A_i^{-1} B_i^{-1}) = s_m(A_i^{-1}).$$

Since  $A_i$  is not an element of order 2,

$$s_m(A_i^{-1}) = -s_m(A_i),$$

and hence  $s_m(B_i A_i^{-1} B_i^{-1}) = -s_m(A_i)$  and

$$s_m(A_i) + s_m(B_i A_i^{-1} B_i^{-1}) = s_m(A_i) - s_m(A_i) = 0.$$

The last statement of the lemma follows from Lemma 4.1.

**Proposition 4.10.** Let  $\Gamma$  be a Fuchsian group of signature  $(g: p_1, \ldots, p_r)$ . Let  $\bar{V} = \{\bar{A}_1, \bar{B}_1, \ldots, \bar{A}_g, \bar{B}_g, \bar{C}_{g+1}, \ldots, \bar{C}_n\}$  be a sequential set that generates  $\Gamma$ . Then there exist lifts of  $\Gamma$  into  $G_m$  if and only if the signature  $(g: p_1, \ldots, p_r)$  satisfies the following liftability conditions:  $\gcd(p_i, m) = 1$  for  $i = 1, \ldots, r$  and

$$(p_1 \cdots p_r) \cdot \left( \sum_{i=1}^r \frac{1}{p_i} - (2g-2) - r \right) \equiv 0 \operatorname{mod} m.$$

Moreover, if the liftability conditions are satisfied then any set of lifts  $\{A_i, B_i\}$  of  $\{\bar{A}_i, \bar{B}_i\}$  into  $G_m$  can be extended in a unique way to a set  $\{A_i, B_i, C_j\}$  of lifts of  $\{\bar{A}_i, \bar{B}_i, \bar{C}_j\}$  that generates a lift of  $\Gamma$  into  $G_m$ , hence there are  $m^{2g}$  different lifts of  $\Gamma$  into  $G_m$ .

*Proof.* Let us first assume that there exists a lift of  $\Gamma$  into  $G_m$ . Let  $\{A_i, B_i, C_j\}$  be a set of lifts of  $\bar{V}$  as in Lemmas 4.8 and 4.9. Let  $n_i = s_m(C_{g+i})$ . Then according to Lemma 4.9 we have  $p_i \cdot n_i + 1 \equiv 0 \mod m$  for  $i = 1, \ldots, r$  and

$$(2g-2) + r + \sum_{i=1}^{r} n_i \equiv 0 \mod m.$$

The first set of congruences implies that  $p_i$  is prime with m for i = 1, ..., r. The last congruence implies that

$$0 \equiv (p_1 \cdots p_r) \cdot \left( (2g - 2) + r + \sum_{i=1}^r n_i \right)$$

$$\equiv (p_1 \cdots p_r) \cdot ((2g - 2) + r) + \sum_{i=1}^r \frac{p_1 \cdots p_r}{p_i} \cdot (p_i \cdot n_i)$$

$$\equiv (p_1 \cdots p_r) \cdot ((2g - 2) + r) + \sum_{i=1}^r \frac{p_1 \cdots p_r}{p_i} \cdot (-1)$$

$$\equiv (p_1 \cdots p_r) \cdot \left( (2g - 2) + r - \sum_{i=1}^r \frac{1}{p_i} \right).$$

Now let us assume that the liftability conditions are satisfied. We want to construct a lift of  $\Gamma$  into  $G_m$ . Since  $p_i$  is prime with m, we can choose  $n_i \in \mathbb{Z}/m\mathbb{Z}$  such that  $p_i \cdot n_i + 1 \equiv 0 \mod m$  for  $i = 1, \ldots, r$ . Then

$$(p_1 \cdots p_r) \cdot \left( (2g - 2) + r + \sum_{i=1}^r n_i \right)$$

$$\equiv (p_1 \cdots p_r) \cdot ((2g - 2) + r) + \sum_{i=1}^r \frac{p_1 \cdots p_r}{p_i} \cdot (p_i n_i)$$

$$\equiv (p_1 \cdots p_r) \cdot ((2g - 2) + r) + \sum_{i=1}^r \frac{p_1 \cdots p_r}{p_i} \cdot (-1)$$

$$\equiv (p_1 \cdots p_r) \cdot \left( (2g - 2) + r - \sum_{i=1}^r \frac{1}{p_i} \right) \equiv 0 \mod m.$$

Since  $\gcd(p_i,m)=1$ , the equality  $(p_1\cdots p_r)\cdot\left((2g-2)+r+\sum\limits_{i=1}^r n_i\right)\equiv 0 \ \mathrm{mod}\ m$  implies  $(2g-2)+r+\sum\limits_{i=1}^r n_i\equiv 0 \ \mathrm{mod}\ m$ , i.e.  $\sum\limits_{i=1}^r n_i\equiv (2-2g)-r \ \mathrm{mod}\ m$ . Let  $V=\{A_i,B_i,C_j\}$  be any set of lifts of  $\bar{V}$  such that  $s_m(C_{g+i})=n_i$  for  $i=1,\ldots,r$ . We have  $p_i\cdot n_i+1\equiv 0 \ \mathrm{mod}\ m$  for  $i=1,\ldots,r$  and  $\sum\limits_{i=1}^r n_i\equiv (2-2g)-r \ \mathrm{mod}\ m$ , hence according to Lemma 4.9 the set V generates a lift of  $\Gamma$  into  $G_m$ . Since Lemma 4.9 does not impose any conditions on the values  $s_m(A_i)$  and  $s_m(B_i)$  for  $i=1,\ldots,g$ , any of  $m^{2g}$  choices of these 2g values leads to a different lift of  $\Gamma$  into  $G_m$ .

### 5. Higher Arf functions

In [NP09] we introduced the notion of a higher Arf function and used it to study moduli spaces of higher spin bundles on Riemann surfaces. In this section we will introduce higher Arf functions on orbifolds, and study their connection with Gorenstein automorphy factors.

5.1. **Definition of higher Arf functions on orbifolds.** In this subsection we will define higher Arf functions on orbifolds (compare with subsection 4.1 in [NP09]).

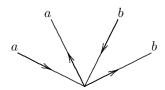


Figure 4:  $\hat{\sigma}(ab) = \hat{\sigma}(a) + \hat{\sigma}(b) + 1$ 

Let  $\Gamma$  be a Fuchsian group of signature  $(g; l_h, l_p, l_e : p_1, \ldots, p_{l_e})$  and  $P = \mathbb{H}/\Gamma$  the corresponding orbifold. Let  $p \in P$ . Let  $\Psi : \mathbb{H} \to P$  be the natural projection. Choose  $q \in \Psi^{-1}(p)$  and let  $\Phi : \Gamma \to \pi(P, p)$  be the induced isomorphism. Let  $\Gamma^*$  be a lift of  $\Gamma$  in  $G_m$ .

**Definition 5.1.** Let us consider a function  $\hat{\sigma}_{\Gamma^*}: \pi(P,p) \to \mathbb{Z}/m\mathbb{Z}$  such that the following diagram commutes

$$\Gamma \xrightarrow{\cong} \Gamma^*$$

$$\Phi \downarrow \qquad \qquad \downarrow s_m|_{\Gamma^*}$$

$$\pi(P, p) \xrightarrow{\hat{\sigma}_{\Gamma^*}} \mathbb{Z}/m\mathbb{Z}$$

**Lemma 5.1.** Let  $\alpha$ ,  $\beta$ , and  $\gamma$  be simple contours in P intersecting pairwise in exactly one point p. Let a, b, and c be the corresponding elements of  $\pi(P,p)$ . We assume that a, b, and c satisfy the relations a, b,  $c \neq 1$  and abc = 1. Let  $\langle \cdot, \cdot \rangle$  be the intersection form on  $\pi(P,p)$ . Then for  $\hat{\sigma} = \hat{\sigma}_{\Gamma^*}$ 

- 1. If the elements a and b can be represented by a pair of simple contours in P intersecting in exactly one point p with  $\langle a,b\rangle \neq 0$ , then  $\hat{\sigma}(ab) = \hat{\sigma}(a) + \hat{\sigma}(b)$ .
- 2. If ab is in  $\pi^0(P,p)$  and the elements a and b can be represented by a pair of simple contours in P intersecting in exactly one point p with  $\langle a,b\rangle=0$  and placed in a neighbourhood of the point p as shown in Figure 4, then  $\hat{\sigma}(ab)=\hat{\sigma}(a)+\hat{\sigma}(b)+1$  if the element ab is not of order 2 and  $\hat{\sigma}(ab)=-\hat{\sigma}(a)-\hat{\sigma}(b)-1$  if the element ab is of order ab.
- 3. if ab is in  $\pi^0(P,p)$  and the elements a and b can be represented by a pair of simple contours in P intersecting in exactly one point p with  $\langle a,b\rangle=0$  and placed in a neighbourhood of the point p as shown in Figure 1, then  $\hat{\sigma}(ab)=\hat{\sigma}(a)+\hat{\sigma}(b)-1$ .
- 4. For any standard basis

$$v = \{a_1, b_1, \dots, a_g, b_g, c_{g+1}, \dots, c_n\}$$

of  $\pi(P, p)$  we have

$$\sum_{i=g+1}^{n} \hat{\sigma}(c_i) \equiv (2-2g) - (n-g) \bmod m.$$

5. For any elliptic element  $c_{g+l_h+l_p+i}$ ,  $i=1,\ldots,l_e$ , we have  $p_i \cdot \hat{\sigma}(c_{g+l_h+l_p+i})+1 \equiv 0 \mod m$ .

*Proof.* According to Theorem 4.4 either the set

$$V = \{\Phi^{-1}(a), \Phi^{-1}(b), \Phi^{-1}(c)\}$$

or the set

$$V^{-1} = \{\Phi^{-1}(a^{-1}), \Phi^{-1}(b^{-1}), \Phi^{-1}(c^{-1})\}$$

is sequential. This sequential set can be of signature (0:\*,\*,\*) or (1:\*).

ullet If V is a sequential set of signature (1:\*), then according to Lemma 3.3 we obtain

$$\hat{\sigma}(ab) = \hat{\sigma}(a) + \hat{\sigma}(b).$$

• If V is a sequential set of signature (0:\*,\*,\*), then according to Corollary 4.7 we obtain

$$\hat{\sigma}(ab) = \hat{\sigma}(a) + \hat{\sigma}(b) + 1$$

if the element ab is not of order 2 and

$$\hat{\sigma}(ab) = -\hat{\sigma}(a) - \hat{\sigma}(b) - 1$$

if the element ab is of order 2.

• If  $V^{-1}$  is a sequential set of signature (0:\*,\*,\*), then according to Corollary 4.7 we obtain,

$$\hat{\sigma}(b^{-1}a^{-1}) = \hat{\sigma}(a^{-1}) + \hat{\sigma}(b^{-1}) + 1$$

if the element ab is not of order 2 and

$$\hat{\sigma}(b^{-1}a^{-1}) = -\hat{\sigma}(a^{-1}) - \hat{\sigma}(b^{-1}) - 1$$

if the element ab is of order 2. Therefore for the element ab not of order 2 we obtain

$$\hat{\sigma}(ab) = -\hat{\sigma}((ab)^{-1}) = -\hat{\sigma}(b^{-1}a^{-1})$$

$$= -(\hat{\sigma}(a^{-1}) + \hat{\sigma}(b^{-1}) + 1)$$

$$= -\hat{\sigma}(a^{-1}) - \hat{\sigma}(b^{-1}) - 1$$

$$= \hat{\sigma}(a) + \hat{\sigma}(b) - 1$$

and for the element ab of order 2 we obtain

$$\hat{\sigma}(ab) = \hat{\sigma}((ab)^{-1}) = \hat{\sigma}(b^{-1}a^{-1})$$
$$= -\hat{\sigma}(a^{-1}) - \hat{\sigma}(b^{-1}) - 1$$
$$= \hat{\sigma}(a) + \hat{\sigma}(b) - 1.$$

To prove properties 4 and 5 of  $\hat{\sigma}$  we apply Lemma 4.9.

We now formalize the properties of the function  $\hat{\sigma}$  in the following definition:

**Definition 5.2.** We denote by  $\pi^0(P, p)$  the set of all non-trivial elements of  $\pi(P, p)$  that can be represented by simple contours. An *m-Arf function* is a function

$$\sigma: \pi^0(P, p) \to \mathbb{Z}/m\mathbb{Z}$$

satisfying the following conditions

- 1.  $\sigma(bab^{-1}) = \sigma(a)$  for any elements  $a, b \in \pi^0(P, p)$ ,
- 2.  $\sigma(a^{-1}) = -\sigma(a)$  for any element  $a \in \pi^0(P, p)$  that is not of order 2,
- 3.  $\sigma(ab) = \sigma(a) + \sigma(b)$  for any elements a and b which can be represented by a pair of simple contours in P intersecting in exactly one point p with  $\langle a, b \rangle \neq 0$ ,
- 4.  $\sigma(ab) = \sigma(a) + \sigma(b) 1$  for any elements  $a, b \in \pi^0(P, p)$  such that the element ab is in  $\pi^0(P, p)$  and the elements a and b can be represented by a pair of simple contours in P intersecting in exactly one point p with  $\langle a, b \rangle = 0$  and placed in a neighbourhood of the point p as shown in Figure 1.
- 5. For any elliptic element c of order p we have  $p \cdot \sigma(c) + 1 \equiv 0 \mod m$ .

The following property of m-Arf functions follows immediately from Properties 4 and 2 in Definition 5.2:

**Proposition 5.2.** Let a and b be elements of  $\pi^0(P,p)$  such that the element ab is in  $\pi^0(P,p)$  and the elements a and b can be represented by a pair of simple contours in P intersecting in exactly one point p with  $\langle a,b\rangle=0$  and placed in a neighbourhood of the point p as shown in Figure 4. Then the equation  $\sigma(ab)=\sigma(a)+\sigma(b)+1$  is satisfied if the element ab is not of order 2 and the equation  $\sigma(ab)=-\sigma(a)-\sigma(b)-1$  is satisfied if the element ab is of order 2.

**Lemma 5.3.** Let  $\Gamma$  be a hyperbolic polygon group of signature  $(0: p_1, \ldots, p_r)$ , r > 3. Let  $c_1, \ldots, c_r$  be a standard basis of  $\Gamma$ . Then the element  $c_1c_2$  is not elliptic.

Proof. Let  $\Pi$  be the canonical fundamental polygon for the group generated by the elements  $c_1, \ldots, c_n$  such that the generators  $c_i$  can be described as products  $c_i = \sigma_i \sigma_{i+1}$  of reflexions  $\sigma_1, \ldots, \sigma_n$  in the edges of the polygon  $\Pi$  (suitably numbered). Then  $c_1 c_2 = (\sigma_1 \sigma_2)(\sigma_2 \sigma_3) = \sigma_1 \sigma_3$ . The product of two reflexions  $\sigma_1 \sigma_2$  is an elliptic element if and only if the axes of the reflexions intersect in  $\mathbb{H}$ . Since r > 3, the sides of the polygon  $\Pi$  that correspond to the reflexions  $\sigma_1$  and  $\sigma_3$  are not next to each other. Let us assume that the axes intersect and let Q be the hyperbolic polygon enclosed between by the axes and the polygon  $\Pi$ . All angles of the polygon  $\Pi$  are acute. One angle of the polygon Q is the angle between the intersecting axes, two angles are larger than  $\pi/2$ , all other angles of Q are larger than  $\pi$ , hence the sum of the angles of Q is larger that it should be for a hyperbolic polygon.

Proposition 5.4. For any standard basis

$$v = \{a_1, b_1, \dots, a_g, b_g, c_{g+1}, \dots, c_{g+l_h+l_p+l_e}\}$$

of  $\pi(P, p)$  we have

$$\sum_{j=q+1}^{n} \sigma(c_j) \equiv (2 - 2g) - (l_h + l_p + l_e) \bmod m.$$

*Proof.* We discuss the case g=0 first, and then we reduce the general case to the case g=0.

• Let g = 0. We prove that the statement is true for lifts of sequential sets of signature  $(0: p_1, \ldots, p_r)$  by induction on r.

In the case r = 3 Proposition 5.2 implies

$$\sigma(c_1c_2) = \sigma(c_1) + \sigma(c_2) + 1$$

if the element  $c_1c_2=c_3^{-1}$  is not of order 2 and

$$\sigma(c_1c_2) = -\sigma(c_1) - \sigma(c_2) - 1$$

if the element  $c_1c_2=c_3^{-1}$  is of order 2. If the element  $c_3$  is not of order 2, then Property 2 implies

$$\sigma(c_1c_2) = \sigma(c_3^{-1}) = -\sigma(c_3).$$

Combining  $\sigma(c_1c_2) = \sigma(c_1) + \sigma(c_2) + 1$  and  $\sigma(c_1c_2) = -\sigma(c_3)$ , we obtain

$$\sigma(c_1) + \sigma(c_2) + \sigma(c_3) = -1.$$

If the element  $c_3$  is of order 2, then

$$\sigma(c_1c_2) = \sigma(c_3^{-1}) = \sigma(c_3).$$

Combining  $\sigma(c_1c_2) = -\sigma(c_1) - \sigma(c_2) - 1$  and  $\sigma(c_1c_2) = \sigma(c_3)$ , we obtain

$$\sigma(c_1) + \sigma(c_2) + \sigma(c_3) = -1.$$

Assume that the statement is true for  $r \leq k-1$  and consider the case r=k. By our assumption

$$\sigma(c_1 \cdot c_2) + \sigma(c_3) + \dots + \sigma(c_k) = 2 - (k-1) = (2-k) + 1.$$

Moreover, according to Lemma 5.3 the element  $c_1c_2$  cannot be of order 2. Hence by Proposition 5.2 we have  $\sigma(c_1c_2) = \sigma(c_1) + \sigma(c_2) + 1$ . The last two equations imply that  $\sigma(c_1) + \cdots + \sigma(c_k) = 2 - k$ .

• We now consider the general case. The set

$$(a_1, b_1 a_1^{-1} b_1^{-1}, \dots, a_g, b_g a_g^{-1} b_g^{-1}, c_{g+1}, \dots, c_{g+r})$$

is a standard basis of an orbifold of signature  $(0:2g+l_h,l_p,l_e:p_1,\ldots,p_{l_e})$ , hence

$$\sum_{i=1}^{g} (\sigma(a_i) + \sigma(b_i a_i^{-1} b_i^{-1})) + \sum_{i=g+1}^{g+l_h + l_p + l_e} \sigma(c_i)$$

$$= 2 - (2g + l_h + l_p + l_e) = (2 - 2g) - (l_h + l_p + l_e).$$

From Properties 1 and 2 of m-Arf functions we obtain that  $\sigma(b_i a_i^{-1} b_i^{-1}) = \sigma(a_i^{-1}) = -\sigma(a_i)$  and hence  $\sigma(a_i) + \sigma(b_i a_i^{-1} b_i^{-1}) = 0$ .

**Definition 5.3.** Let  $\hat{\sigma}_{\Gamma^*}: \pi(P,p) \to \mathbb{Z}/m\mathbb{Z}$  be the function associated to a lift  $\Gamma^*$  as in definition 5.1, then the function  $\sigma_{\Gamma^*} = \hat{\sigma}_{\Gamma^*}|_{\pi^0(P,p)}$  is an m-Arf function according to Lemma 5.1, 3.1, and 3.2. We call the function  $\sigma_{\Gamma^*}$  the m-Arf function associated to the lift  $\Gamma^*$ .

5.2. Higher Arf functions and autohomeomorphisms of orbifolds. Let  $\Gamma$  be a Fuchsian group of signature  $(g:p_1,\ldots,p_r)$  and  $P=\mathbb{H}/\Gamma$  the corresponding orbifold. Let  $p \in P$ . Let  $\Psi: \mathbb{H} \to P$  be the natural projection. Choose  $q \in \Psi^{-1}(p)$  and let  $\Phi: \Gamma \to \pi^0(P,p)$  be the induced isomorphism. Let  $\Gamma^*$  be a lift of  $\Gamma$  in  $G_m$ .

Consider the following transformations of a standard basis:

$$v = \{a_1, b_1, \dots, a_g, b_g, c_{g+1}, \dots, c_n\}$$

of  $\pi^0(P,p)$  to another standard basis

$$v' = \{a'_1, b'_1, \dots, a'_q, b'_q, c'_{q+1}, \dots, c'_n\}$$
:

1. 
$$a'_1 = a_1b_1$$
.  
2.  $a'_1 = (a_1a_2)a_1(a_1a_2)^{-1}$ ,  
 $b'_1 = (a_1a_2)a_1^{-1}a_2^{-1}b_1(a_1a_2)^{-1}$ ,  
 $a'_2 = a_1a_2a_1^{-1}$ ,  
 $b'_2 = b_2a_2^{-1}a_1^{-1}$ .  
3.  $a'_g = (b_g^{-1}c_{g+1})b_g^{-1}(b_g^{-1}c_{g+1})^{-1}$ ,  
 $b'_g = (b_g^{-1}c_{g+1}b_g)c_{g+1}^{-1}b_ga_gb_g^{-1}(b_g^{-1}c_{g+1}b_g)^{-1}$ ,  
 $c'_{g+1} = b_g^{-1}c_{g+1}b_g$ .  
4.  $a'_k = a_{k+1}$ ,  $b'_k = b_{k+1}$ ,  
 $a'_{k+1} = (c_{k+1}^{-1}c_k)a_k(c_{k+1}^{-1}c_k)^{-1}$ ,  
 $b'_{k+1} = (c_{k+1}^{-1}c_k)b_k(c_{k+1}^{-1}c_k)^{-1}$ .  
5.  $c'_k = c_{k+1}$ ,  $c'_{k+1} = c_{k+1}^{-1}c_kc_{k+1}$ .

Here  $c_i = [a_i, b_i]$  for i = 1, ..., g, in 4 we consider  $k \in \{1, ..., g\}$ , in 5 we consider  $k \in \{g + 1, ..., n\}$  such that  $\operatorname{ord}(c_k) = \operatorname{ord}(c_{k+1})$ . If  $a'_i, b'_i$  resp.  $c'_i$  is not described explicitly, this means  $a'_i = a_i, b'_i = b_i$  resp.  $c'_i = c_i$ .

We will call these transformations generalised Dehn twists. Each generalised Dehn twists induces a homotopy class of autohomeomorphisms of the orbifold P, which maps elliptic fixed points to elliptic fixed points of the same order. The group of all homotopy classes of autohomeomorphisms of the orbifold P is generated by the homotopy classes of generalised Dehn twists as described above (compare [Zie73]).

Now we will compute the values of an Arf function  $\sigma$  on the standard basis v' from the values of  $\sigma$  on the standard basis v for each of the generalised Dehn twists described above.

**Lemma 5.5.** Let  $\sigma: \pi^0(P,p) \to \mathbb{Z}/m\mathbb{Z}$  be an m-Arf function. Let D be a generalised Dehn twist of the type described above. Suppose that D maps the standard basis

$$v = \{a_1, b_1, \dots, a_q, b_q, c_{q+1}, \dots, c_n\}$$

into the standard basis

$$v' = D(v) = \{a'_1, b'_1, \dots, a'_g, b'_g, c'_{g+1}, \dots, c'_n\}.$$

Let  $\alpha_i, \beta_i, \gamma_i$  resp.  $\alpha'_i, \beta'_i, \gamma'_i$  be the values of  $\sigma$  on the elements of v resp. v'. Then for the Dehn twists of types 1–5 we obtain

1. 
$$\alpha_1' = \alpha_1 + \beta_1$$
.

2. 
$$\beta_1' = \beta_1 - \alpha_1 - \alpha_2 - 1$$
,  $\beta_2' = \beta_2 - \alpha_2 - \alpha_1 - 1$ .

3. 
$$\alpha'_g = -\beta_g$$
,  $\beta'_g = \alpha_g - \gamma_{g+1} - 1$ .

4. 
$$\alpha'_{k} = \alpha_{k+1}$$
,  $\beta'_{k} = \beta_{k+1}$ ,  $\alpha'_{k+1} = \alpha_{k}$ ,  $\beta'_{k+1} = \beta_{k}$ .

5. 
$$\gamma'_k = \gamma_{k+1}, \quad \gamma'_{k+1} = \gamma_k.$$

*Proof.* We assume that the Dehn twist D belongs to one of the types described in the definition above. In the following computations we illustrate the position

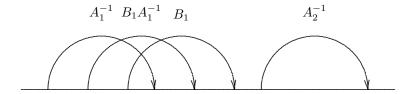


Figure 5: Axes of  $B_1A_1^{-1}$  and  $A_2^{-1}$ 

of the contours on the surface with figures showing the position of the axes of the corresponding elements in  $\Gamma$ . Let

$$\{A_1, B_1, \dots, A_q, B_q, C_{q+1}, \dots, C_n\}$$

be the sequential set corresponding to the standard basis v. In the first case according to Property 3 of m-Arf functions we obtain

$$\sigma(a_1') = \sigma(a_1b_1) = \sigma(a_1) + \sigma(b_1).$$

In the second case according to Property 1 we obtain

$$\sigma(a_1') = \sigma((a_1 a_2) a_1 (a_1 a_2)^{-1}) = \sigma(a_1),$$
  

$$\sigma(b_1') = \sigma((a_1 a_2) a_1^{-1} a_2^{-1} b_1 (a_1 a_2)^{-1}) = \sigma(a_1^{-1} a_2^{-1} b_1)$$
  

$$= \sigma(a_1 (a_1^{-1} a_2^{-1} b_1) a_1^{-1}) = \sigma(a_2^{-1} b_1 a_1^{-1}).$$

The mutual position of the axes of the elements  $A_2^{-1}$  and  $B_1A_1^{-1}$  is as in Figure 5, hence Property 4 implies

$$\sigma(b_1') = \sigma(a_2^{-1} \cdot (b_1 a_1^{-1})) = \sigma(a_2^{-1}) + \sigma(b_1 a_1^{-1}) - 1.$$

According to Property 3 we have  $\sigma(b_1a_1^{-1}) = \sigma(b_1) + \sigma(a_1^{-1})$ . Thus using Property 2 we obtain

$$\sigma(b_1') = \sigma(a_2^{-1}) + \sigma(b_1) + \sigma(a_1^{-1}) - 1 = \sigma(b_1) - \sigma(a_1) - \sigma(a_2) - 1.$$

Similarly we show that  $\sigma(a_2) = \sigma(a_2)$  and  $\sigma(b_2) = \sigma(b_2) - \sigma(a_2) - \sigma(a_1) - 1$ .

In the third case we obtain according to Properties 2 and 1  $\,$ 

$$\begin{split} &\sigma(a_g') = \sigma((b_g^{-1}c_{g+1})b_g^{-1}(b_g^{-1}c_{g+1})^{-1}) = \sigma(b_g^{-1}) = -\sigma(b_g),\\ &\sigma(b_g') = \sigma((b_g^{-1}c_{g+1}b_g)c_{g+1}^{-1}b_ga_gb_g^{-1}(b_g^{-1}c_{g+1}b_g)^{-1}) = \sigma(c_{g+1}^{-1}b_ga_gb_g^{-1}),\\ &\sigma(c_{g+1}') = \sigma(b_g^{-1}c_{g+1}b_g) = \sigma(c_{g+1}). \end{split}$$

The mutual position of the axes of the elements  $C_{g+1}^{-1}$  and  $B_g A_g B_g^{-1}$  is as in Figure 6. According to Properties 4 and 1 we obtain

$$\sigma(b_g') = \sigma(c_{g+1}^{-1} \cdot (b_g a_g b_g^{-1})) = \sigma(c_{g+1}^{-1}) + \sigma(b_g a_g b_g^{-1}) - 1 = \sigma(c_{g+1}^{-1}) + \sigma(a_g) - 1.$$

In the forth and fifth case computations are easy, we only use Property 1 of m-Arf functions.

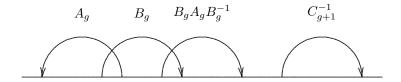


Figure 6: Axes of  $C_{g+1}^{-1}$  and  $B_g A_g B_g^{-1}$ 

5.3. Correspondence between higher Arf functions and hyperbolic Gorenstein automorphy factors. Let  $\Gamma$  be a Fuchsian group of signature  $(g:p_1,\ldots,p_r)$  and  $P=\mathbb{H}/\Gamma$  the corresponding orbifold. Let  $p\in P$ . Let  $\Psi:\mathbb{H}\to P$  be the natural projection. Choose  $q\in \Psi^{-1}(p)$  and let  $\Phi:\Gamma\to \pi^0(P,p)$  be the induced isomorphism.

**Lemma 5.6.** The difference  $\sigma_1 - \sigma_2 : \pi^0(P, p) \to \mathbb{Z}/m\mathbb{Z}$  of two Arf functions  $\sigma_1$  and  $\sigma_2$  induces a linear function  $\ell : H_1(P; \mathbb{Z}/m\mathbb{Z}) \to \mathbb{Z}/m\mathbb{Z}$ .

*Proof.* The proof is analogous to the proof of the corresponding statement for higher Arf functions on Fuchsian groups without torsion (see Lemma 4.5 in [NP09]). The main observation is the fact that according to Lemma 5.5 the action of the generalised Dehn twists on the tuples of values of a higher Arf function on elements of a standard basis are by affine-linear maps, therefore the action on the tuples of differences of values of two higher Arf functions is by linear maps.  $\Box$ 

**Corollary 5.7.** The set  $\operatorname{Arf}^{P,m}$  of all m-Arf functions on  $\pi^0(P,p)$  has a structure of an affine space, i.e. the set  $\{\sigma - \sigma_0 \mid \sigma \in \operatorname{Arf}^{P,m}\}$  is a free module over  $\mathbb{Z}/m\mathbb{Z}$  for any  $\sigma_0 \in \operatorname{Arf}^{P,m}$ .

**Corollary 5.8.** An m-Arf function is uniquely determined by its values on the elements of some standard basis of  $\pi^0(P,p)$ .

**Theorem 5.9.** Let  $\Gamma$  be a Fuchsian group of signature  $(g: p_1, \ldots, p_r)$  and  $P = \mathbb{H}/\Gamma$  the corresponding orbifold. Let  $p \in P$ . There is a 1-1-correspondence between

- 1) hyperbolic Gorenstein automorphy factors of level m associated to the Fuchsian group  $\Gamma$ .
- 2) lifts of  $\Gamma$  into  $G_m$ .
- 3) m-Arf functions  $\sigma: \pi^0(P, p) \to \mathbb{Z}/m\mathbb{Z}$ .

*Proof.* According to Proposition 2.4 there is a 1-1-correspondence between hyperbolic Gorenstein automorphy factors of level m associated to the Fuchsian group  $\Gamma$  and the lifts of  $\Gamma$  into  $G_m$ . In Definition 5.1 we attached to any lift  $\Gamma^*$  of  $\Gamma$  into  $G_m$  an m-Arf function  $\sigma_{\Gamma^*}$  on P. On the other hand we can attach to any m-Arf function  $\sigma$  a subset of  $G_m$ 

$$\Gamma_{\sigma}^* = \{ g \in G_m \mid \pi(g) \in \Gamma, \ s_m(g) = \sigma(\Phi(\pi(g))) \},$$

where  $\pi: G_m \to G$  is the covering map. It remains to prove that this subset of  $G_m$  is actually a lift of  $\Gamma$ . Let

$$v = \{a_1, b_1, \dots, a_q, b_q, c_{q+1}, \dots, c_{q+r}\} = \{d_1, \dots, d_{2q+r}\}$$

be a standard basis of  $\pi(P,p)$  and let  $\bar{V}=\{\Phi^{-1}(d_1),\ldots,\Phi^{-1}(d_{2g+r})\}$  be the corresponding sequential set. Let  $\{D_j\}_{j=1,\ldots,2g+r}$  be a lift of the sequential set  $\bar{V}$ , i.e.  $\pi(D_j)=\Phi^{-1}(d_j)$ , such that  $s_m(D_j)=\sigma(d_j)$ . Then we obtain according to Proposition 5.4 that

$$\sum_{i=g+1}^{n} s_m(C_i) = \sum_{i=g+1}^{n} \sigma(c_i) = (2-2g) - (n-g) \bmod m,$$

hence by Lemma 4.9 we obtain

$$\prod_{i=1}^{g} [A_i, B_i] \cdot \prod_{i=g+1}^{n} C_i = e.$$

This and the fact that for any i = 1, ..., r

$$p_i \cdot s_m(C_{g+i}) + 1 = p_i \cdot \sigma(c_{g+i}) + 1 \equiv 0 \mod m$$

imply according to Lemma 4.8 that the subgroup  $\Gamma^*$  of  $G_m$  generated by V is a lift of  $\Gamma$  into  $G_m$ . Let us compare the corresponding Arf function  $\sigma_{\Gamma^*}$  with the Arf function  $\sigma$ . We have

$$\sigma_{\Gamma^*}(d_j) = s_m(D_j) = \sigma(d_j)$$

for all j i.e. the Arf functions  $\sigma_{\Gamma^*}$  and  $\sigma$  coincide on the standard basis v. Thus by Lemma 5.6 the Arf functions  $\sigma_{\Gamma^*}$  and  $\sigma$  coincide on the whole  $\pi^0(P,p)$ . From the definition of  $\sigma_{\Gamma^*}$  and  $\Gamma^*_{\sigma}$  we see that this implies that  $\Gamma^* = \Gamma^*_{\sigma}$ , hence  $\Gamma^*_{\sigma}$  is indeed a lift of  $\Gamma$  into  $G_m$ . It is clear from the definitions that the mappings  $\Gamma^* \mapsto \sigma_{\Gamma^*}$  and  $\sigma \mapsto \Gamma^*_{\sigma}$  are inverse to each other.

Corollary 5.10. Let P be a Riemann orbifold of signature  $(g: p_1, \ldots, p_r)$ . Let  $v = \{a_1, b_1, \ldots, a_g, b_g, c_{g+1}, \ldots, c_{g+r}\}$  be a standard basis of  $\pi(P, p)$ . An m-Arf function on  $\pi^0(P, p)$  exists if and only if the signature  $(g: p_1, \ldots, p_r)$  satisfies the liftability conditions described in Proposition 4.10. Moreover, if the liftability conditions are satisfied then any possible tuple of 2g values in  $\mathbb{Z}/m\mathbb{Z}$  can be realised in a unique way as a set of values on  $a_i, b_i$  of an m-Arf function on  $\pi^0(P, p)$ , hence there are  $m^{2g}$  different m-Arf functions on  $\pi^0(P, p)$ .

 ${\it Proof.}$  The statement follows immediately from Theorem 5.9 and Proposition 4.10.

### 6. Moduli spaces of Gorenstein singularities

We study the moduli space of Gorenstein quasi-homogeneous surface singularities (GQHSS). Using Proposition 2.4, we define the moduli space of GQHSS of level m as the space of conjugacy classes of subgroups  $\Gamma^*$  in  $G_m$  such that the restriction of the covering map  $G_m \to G = \mathrm{PSL}(2,\mathbb{R})$  to  $\Gamma^*$  is an isomorphism between  $\Gamma^*$  and a Fuchsian group  $\Gamma$ . The projection  $\Gamma^* \to \Gamma$  from the moduli space of GQHSS of level m to the moduli space of Riemann orbifolds is a finite ramified covering.

6.1. Topological classification of higher Arf functions. There is a 1-1-correspondence (see Theorem 5.9) between automorphy factors of level m and m-Arf functions on  $\pi^0(P,p)$ . This correspondence allows us to reduce the problem of finding the number of connected components of the moduli space of GQHSS of level m to the problem of finding the number of orbits of the action of the group of autohomeomorphisms on the set of m-Arf functions. We describe the orbit of an m-Arf function under the action of the group of homotopy classes of surface autohomeomorphisms.

Let P be a Riemann orbifold of signature  $(g: p_1, \ldots, p_r)$ . Let  $p \in P$ .

**Definition 6.1.** Let  $\sigma: \pi^0(P, p) \to \mathbb{Z}/m\mathbb{Z}$  be an m-Arf function. We define the Arf invariant  $\delta = \delta(P, \sigma)$  of  $\sigma$  as follows: If g > 1 and m is even then we set  $\delta = 0$  if there is a standard basis  $\{a_1, b_1, \ldots, a_g, b_g, c_{g+1}, \ldots, c_n\}$  of the fundamental group  $\pi(P, p)$  such that

$$\sum_{i=1}^{g} (1 - \sigma(a_i))(1 - \sigma(b_i)) \equiv 0 \mod 2$$

and we set  $\delta=1$  otherwise. If g>1 and m is odd then we set  $\delta=0$ . If g=0 then we set  $\delta=0$ . If g=1 then we set

$$\delta = \gcd(m, p_1 - 1, \dots, p_r - 1, \sigma(a_1), \sigma(b_1)),$$

where  $\{a_1, b_1, c_2, \dots, c_{r+1}\}$  is a standard basis of the fundamental group  $\pi(P, p)$ .

Remark. It is not hard to see that  $\delta$  does not change under the transformations described in Lemma 5.5, i.e. it is indeed an invariant of the Arf function.

*Proof.* Let D, v, v',  $\alpha_i$ ,  $\beta_i$ ,  $\gamma_i$ ,  $\alpha_i'$ ,  $\beta_i'$ ,  $\gamma_i'$  be as in Lemma 5.5. Let us first consider the case g > 1: For a Dehn twist of type 1 we have

$$(1 - \alpha_1')(1 - \beta_1') = (1 - (\alpha_1 + \beta_1))(1 - \beta_1)$$
  
=  $(1 - \alpha_1)(1 - \beta_1) - \beta_1(1 - \beta_1) \equiv (1 - \alpha_1)(1 - \beta_1) \bmod 2.$ 

For a Dehn twist of type 2 we have

$$(1 - \alpha_1')(1 - \beta_1') + (1 - \alpha_2')(1 - \beta_2')$$

$$= (1 - \alpha_1)(1 - \beta_1 + \alpha_1 + \alpha_2 + 1) + (1 - \alpha_2)(1 - \beta_2 + \alpha_1 + \alpha_2 + 1)$$

$$= (1 - \alpha_1)(1 - \beta_1) + (1 - \alpha_2)(1 - \beta_2) + (2 - (\alpha_1 + \alpha_2))((\alpha_1 + \alpha_2) + 1)$$

$$\equiv (1 - \alpha_1)(1 - \beta_1) + (1 - \alpha_2)(1 - \beta_2) \mod 2.$$

For a Dehn twist of type 3, since m is even and  $p_1 \cdot \gamma_{g+1} + 1 \equiv 0 \mod m$ , we have that  $\gamma_{g+1}$  is odd. Then

$$(1-\alpha_g')(1-\beta_g') = (1+\beta_g)(1-\alpha_g+(\gamma_{g+1}+1)) \equiv (1+\beta_g)(1-\alpha_g) \equiv (1-\beta_g)(1-\alpha_g)$$
 since  $\gamma_{g+1}+1 \equiv 0 \mod 2$  and  $1+\beta_g \equiv 1-\beta_g \mod 2$ . Dehn twists of type 4 do not change  $\sum_{i=1}^g (1-\sigma(a_i))(1-\sigma(b_i))$  since they only permute  $(\alpha_k,\beta_k)$  with  $(\alpha_{k+1},\beta_{k+1})$ . Dehn twists of type 5 do not change  $\sum_{i=1}^g (1-\sigma(a_i))(1-\sigma(b_i))$  since they only permute  $\gamma_i$ .

Let us now consider the case g=1: Dehn twists of types 2 and 4 involve pairs  $a_i, b_i$  and  $a_j, b_j$ , i.e. they are not applicable in the case g=1. Dehn twist of type 5 only swaps the orders of two elliptic fixed points, hence it does not change  $\delta$ . For a Dehn twist of type 1 we obtain  $\alpha'_1 = \alpha_1 + \beta_1$  and  $\beta'_1 = \beta_1$ . Thus

$$gcd(\alpha'_1, \beta'_1) = gcd(\alpha_1 + \beta_1, \beta_1) = gcd(\alpha_1, \beta_1)$$

and therefore  $\gcd(m, p_1 - 1, \dots, p_r - 1, \alpha'_1, \beta'_1) = \gcd(m, p_1 - 1, \dots, p_r - 1, \alpha_1, \beta_1)$ . For a Dehn twist of type 3 we obtain  $\alpha'_1 = -\beta_1$  and  $\beta'_1 = \alpha_1 - \gamma_2 - 1$ . Let d be a common divisor of  $m, p_1 - 1, \dots, p_r - 1, \alpha_1, \beta_1$ , i.e

$$m \equiv \alpha_1 \equiv \beta_1 \equiv 0 \mod d$$
,  $p_1 \equiv \cdots \equiv p_r \equiv 1 \mod d$ .

We know that  $p_1 \cdot \gamma_2 + 1 \equiv 0 \mod m$ , but  $m \equiv 0 \mod d$ , hence  $p_1 \cdot \gamma_2 + 1 \equiv 0 \mod d$ . Since  $p_1 \equiv 1 \mod d$ , we obtain that  $\gamma_2 + 1 \equiv 0 \mod d$ . Hence d is a common divisor of  $m, p_1 - 1, \ldots, p_r - 1, \alpha'_1 = -\beta_1, \beta'_1 = \alpha_1 - (\gamma_2 + 1)$ . Similarly every common divisor of  $m, p_1 - 1, \ldots, p_r - 1, \alpha'_1, \beta'_1$  is a common divisor of  $m, p_1 - 1, \ldots, p_r - 1, \alpha_1, \beta_1$ . Thus

$$\gcd(m, p_1 - 1, \dots, p_r - 1, \alpha'_1, \beta'_1) = \gcd(m, p_1 - 1, \dots, p_r - 1, \alpha_1, \beta_1).$$

**Definition 6.2.** By the type of the m-Arf function  $(P, \sigma)$  we mean the tuple

$$(g, p_1, \ldots, p_r, \delta),$$

where  $\delta$  is the Arf invariant of  $\sigma$  defined above.

**Lemma 6.1.** Let  $\sigma: \pi^0(P,p) \to \mathbb{Z}/m\mathbb{Z}$  be an m-Arf function.

(a) If g > 1 then there is a standard basis  $v = \{a_1, b_1, \dots, a_g, b_g, c_{g+1}, \dots, c_n\}$  of  $\pi(P, p)$  such that

$$(\sigma(a_1), \sigma(b_1), \dots, \sigma(a_g), \sigma(b_g)) = (0, \xi, 1, \dots, 1)$$

with  $\xi \in \{0,1\}$ . If m is odd then the basis can be chosen in such a way that  $\xi = 1$ , i.e. so that

$$(\sigma(a_1), \sigma(b_1), \dots, \sigma(a_q), \sigma(b_q)) = (0, 1, 1, \dots, 1)$$

(b) If g = 1 then there is a standard basis  $v = \{a_1, b_1, c_2, \ldots, c_n\}$  of  $\pi(P, p)$  such that  $(\sigma(a_1), \sigma(b_1)) = (\delta, 0)$ , where  $\delta$  is the Arf invariant of  $\sigma$ .

*Proof.* The proof is along the lines of the proofs of Lemma 5.1 and Lemma 5.2 in [NP09]. Using generalised Dehn twists of types 1,2 and 4 we can show that a basis can be chosen in the desired way. The last step in the proof of Lemma 5.1 in [NP09] was to show that if m is even and  $\sigma(c_{g+1})$  is even then we can transform a basis with

$$(\sigma(a_1), \sigma(b_1), \dots, \sigma(a_q), \sigma(b_q)) = (0, 0, 1, \dots, 1)$$

into the basis with

$$(\sigma(a_1), \sigma(b_1), \dots, \sigma(a_q), \sigma(b_q)) = (0, 1, 1, \dots, 1).$$

However in the situation we are considering now we know that  $\sigma(c_i)$  satisfies the equation  $p_i \cdot \sigma(c_i) + 1 \equiv 0 \mod m$ . Therefore if m is even then  $\sigma(c_i)$  must be odd. Hence this last reduction step does not apply in the case considered here.

Remark. An autohomeomorphism of a surface P induces an automorphism of the lifted Fuchsian group. Let  $\mathcal{A}$  be the corresponding group of such automorphisms of lifts of Fuchsian groups. On the other hand, any autohomeomorphism generates an element of  $\mathrm{Sp}(2g,\mathbb{Z})$ , where g is the genus of P. Lemma 6.1 implies that for two autohomeomorphisms the corresponding elements in  $\mathcal{A}$  differ if the corresponding elements in  $\mathrm{Sp}(2g,\mathbb{Z}_m)$  differ. Thus we obtain a homomorphism  $f:\mathcal{A}\to\mathrm{Sp}(2g,\mathbb{Z}_m)$ . Using generalised Dehn twists of types 1,2 and 4 we can show that f is an epimorphism. Lemma 6.1 implies that  $\ker(f)=d\cdot T$ , where T is the group of all parallel translations on the affine space of all lifts. Using Dehn twists of types 1–5 and

Lemma 6.1 we are able to determine the number d. If g > 1 then d = 2 if m is even and d = 1 otherwise. If g = 1 then  $d = \gcd(m, p_1 - 1, \dots, p_r - 1, \sigma(a_1), \sigma(b_1))$ .

**Theorem 6.2.** A tuple  $t = (g, p_1, ..., p_r, \delta)$  is the type of a hyperbolic m-Arf function on a Riemann orbifold of signature  $(g : p_1, ..., p_r)$  if and only if it has the following properties:

(a) The liftability conditions: The orders  $p_1, \ldots, p_r$  are prime with m and satisfy the condition

$$(p_1 \cdots p_r) \cdot \left( \sum_{i=1}^r \frac{1}{p_i} - (2g-2) - r \right) \equiv 0 \operatorname{mod} m.$$

- (b) If g > 1 then  $\delta \in \{0, 1\}$ .
- (c) If g > 1 and m is odd then  $\delta = 0$ .
- (d) If g = 1 then  $\delta$  is a divisor of  $gcd(m, p_1 1, \dots, p_r 1)$ .
- (e) If g = 0 then  $\delta = 0$ .

*Proof.* Let us first assume that the tuple t is a type of a hyperbolic m-Arf function on a orbifold of signature  $(g:p_1,\ldots,p_r)$ . Then according to Corollary 5.10 the signature  $(g:p_1,\ldots,p_r)$  satisfies the liftability conditions. If g>1 and m is odd then according to Lemma 6.1 there is a standard basis  $\{a_1,b_1,\ldots,a_g,b_g,c_{g+1},\ldots,c_{g+r}\}$  of  $\pi^0(P,p)$  such that

$$(\sigma(a_1), \sigma(b_1), \dots, \sigma(a_q), \sigma(b_q)) = (0, 1, 1, \dots, 1),$$

hence  $\delta(P, \sigma) = 0$  by definition. If g = 1 then  $\delta$  is a divisor of  $m, p_1 - 1, \dots, p_r - 1$  by definition. If g = 0 then  $\delta = 0$  by definition.

Now let us assume that  $t = (g, p_1, \dots, p_r, \delta)$  satisfies the conditions (a)-(e). Let P be a Riemann orbifold of signature  $(g: p_1, \dots, p_r)$  and let

$$\{a_1, b_1, \dots, a_g, b_g, c_{g+1}, \dots, c_{g+r}\}$$

be a standard basis of  $\pi^0(P, p)$ . According to Corollary 5.10 any tuple of 2g values in  $\mathbb{Z}/m\mathbb{Z}$  can be realised as a set of values on  $a_i, b_i$  of an m-Arf function on  $\pi^0(P, p)$ , In particular if g > 1 then for any  $\delta \in \{0, 1\}$  there exists an m-Arf function  $\sigma^{\delta}$  such that  $(\sigma^{\delta}(a_1), \sigma^{\delta}(b_1), \ldots, \sigma^{\delta}(a_g), \sigma^{\delta}(b_g)) = (0, 1 - \delta, 1, \ldots, 1)$  and if g = 1 then for any divisor  $\delta$  of  $m, p_1 - 1, \ldots, p_r - 1$  there exists an m-Arf function  $\sigma^{\delta}$  such that  $(\sigma^{\delta}(a_1), \sigma^{\delta}(b_1)) = (\delta, 0)$ .

Let g > 1. If  $\delta = 0$  then the equation  $\delta(\sigma^0) = 0$  is satisfied by definition. If  $\delta = 1$  and m is even, it remains to prove that  $\delta(\sigma^1) = 1$ . To this end we recall that  $\sum_{i=1}^{g} (1 - \sigma(a_i))(1 - \sigma(b_i)) \mod 2$  is preserved under the Dehn twists and hence is equal to 1 modulo 2 for any standard basis.

Now let 
$$g = 1$$
. Then  $\delta(\sigma^{\delta}) = \gcd(m, p_1 - 1, \dots, p_r - 1, \delta, 0) = \delta$  since  $\delta$  is a divisor of  $\gcd(m, p_1 - 1, \dots, p_r - 1)$ .

6.2. **Teichmüller spaces of Fuchsian groups.** We recall the results on the moduli spaces of Fuchsian groups from [Zie81].

Let  $\Gamma_{q;p_1,...,p_r}$  be the group generated by the elements

$$v = \{a_1, b_1, \dots, a_g, b_g, c_{g+1}, \dots, c_{g+r}\}$$

with defining relations

$$\prod_{i=1}^{g} [a_i, b_i] \prod_{i=q+1}^{g+r} c_i = 1, \quad c_{g+1}^{p_1} = \dots = c_{g+r}^{p_r} = 1.$$

We denote by  $\tilde{T}_{g;p_1,...,p_r}$  the set of monomorphisms  $\psi:\Gamma_{g;p_1,...,p_r}\to \operatorname{Aut}(\mathbb{H})$  such that

$$\psi(v) = \{a_1^{\psi}, b_1^{\psi}, \dots, a_g^{\psi}, b_g^{\psi}, c_{g+1}^{\psi}, \dots, c_{g+r}^{\psi}\}$$

is a sequential set of signature  $(g; p_1, \ldots, p_r)$ . Here we assume that g > 1.

The group  $\operatorname{Aut}(\mathbb{H})$  acts on  $\tilde{T}_{g;p_1,\dots,p_r}$  by conjugation. We set

$$T_{g;p_1,...,p_r} = \tilde{T}_{g;p_1,...,p_r} / \operatorname{Aut}(\mathbb{H}).$$

We parametrise the space  $\tilde{T}_{g;p_1,...,p_r}$  by the fixed points and shift parameters of the elements of the sequential sets  $\psi(v)$ . We use here the following analogue of a version [Nat78], [Nat04] of the Theorem of Fricke and Klein [FK65]:

**Theorem 6.3.** The space  $T_{g;p_1,...,p_r}$  is diffeomorphic to an open domain in  $\mathbb{R}^{6g-6+2r}$ 

which is homeomorphic to  $\mathbb{R}^{6g-6+2r}$ .

For an element  $\psi: \Gamma_{g;p_1,...,p_r} \to \operatorname{Aut}(\mathbb{H})$  of  $\tilde{T}_{g;p_1,...,p_r}$  we write

$$\widetilde{\mathrm{Mod}}^{\psi} = \widetilde{\mathrm{Mod}}_{g;p_1,\dots,p_r}^{\psi} = \{\alpha \in \mathrm{Aut}(\Gamma_{g;p_1,\dots,p_r}) \ \big| \ \psi \circ \alpha \in \tilde{T}_{g;p_1,\dots,p_r} \}.$$

One can show that  $\widetilde{\mathrm{Mod}}^{\psi}$  does not depend on  $\psi$ , hence we write  $\widetilde{\mathrm{Mod}}$  instead of  $\widetilde{\mathrm{Mod}}^{\psi}$ . Let  $I\widetilde{\mathrm{Mod}}$  be the subgroup of all inner automorphisms of  $\Gamma_{g;p_1,\ldots,p_r}$  and let

$$\operatorname{Mod}_{q;p_1,\ldots,p_r} = \operatorname{Mod} = \widetilde{\operatorname{Mod}}/I\widetilde{\operatorname{Mod}}.$$

We now recall the description of the moduli space of Riemann orbifolds

**Theorem 6.4.** The group  $\operatorname{Mod} = \operatorname{Mod}_{g;p_1,\dots,p_r}$  and the group of homotopy classes of orientation preserving autohomeomorphisms of the orbifold of signature  $(g:p_1,\dots,p_r)$  are naturally isomorphic. The group  $\operatorname{Mod}_{g;p_1,\dots,p_r}$  acts naturally on  $T_{g;p_1,\dots,p_r}$  by diffeomorphisms. This action is discrete. The quotient set

$$T_{g;p_1,\ldots,p_r}/\operatorname{Mod}_{g;p_1,\ldots,p_r}$$

can be identified naturally with the moduli space  $M_{g;p_1,...,p_r}$  of Riemann orbifolds of signature  $(g:p_1,...,p_r)$ .

## 6.3. Connected components of the moduli space.

**Definition 6.3.** We denote by  $S^m(t) = S^m(g, p_1, \ldots, p_r, \delta)$  the set of all GQHSS of level m and signature  $(g: p_1, \ldots, p_r)$  such that the associated m-Arf function is of type  $t = (g, p_1, \ldots, p_r, \delta)$ .

**Theorem 6.5.** Let  $t = (g, p_1, \ldots, p_r, \delta)$  be a tuple that satisfies the conditions of Theorem 6.2, i.e. the space  $S^m(t)$  is not empty. Then the space  $S^m(t)$  is homeomorphic to  $T_{g;p_1,\ldots,p_r}/\operatorname{Mod}_{g;p_1,\ldots,p_r}^m(t)$ , where  $T_{g;p_1,\ldots,p_r}$  is homeomorphic to  $\mathbb{R}^{6g-6+2r}$  and  $\operatorname{Mod}_{g;p_1,\ldots,p_r}^m(t)$  acts on  $T_{g;p_1,\ldots,p_r}$  as a subgroup of finite index in the group  $\operatorname{Mod}_{g;p_1,\ldots,p_r}$ .

*Proof.* Let us consider an element  $\psi$  of the space  $T_{g;p_1,\dots,p_r}$ . By definition  $\psi$  is an homomorphism  $\psi: \Gamma_{g;p_1,\dots,p_r} \to \operatorname{Aut}(\mathbb{H})$ . To the homomorphism  $\psi$  we attach an orbifold  $P_{\psi} = \mathbb{H}/\psi(\Gamma_{g;p_1,\dots,p_r})$ , a standard basis

$$v_{\psi} = \{a_1^{\psi}, b_1^{\psi}, \dots, a_q^{\psi}, b_q^{\psi}, c_{q+1}^{\psi}, \dots, c_{q+r}^{\psi}\}$$

of  $\pi(P_{\psi}, p)$  and an m-Arf function  $\sigma_{\psi}$  on this surface given by

$$(\sigma_{\psi}(a_{1}^{\psi}), \sigma_{\psi}(b_{1}^{\psi})) = (\delta, 0) \quad \text{if} \quad g = 1, (\sigma_{\psi}(a_{1}^{\psi}), \sigma_{\psi}(b_{1}^{\psi}), \sigma_{\psi}(a_{2}^{\psi}), \sigma_{\psi}(b_{2}^{\psi}), \dots, \sigma_{\psi}(a_{g}^{\psi}), \sigma_{\psi}(b_{g}^{\psi})) = (0, 1 - \delta, 1, \dots, 1) \quad \text{if} \quad g > 1.$$

By Theorem 5.9, the *m*-Arf function  $\sigma_{\psi}$  on the orbifold  $P_{\psi}$  corresponds to a lift of  $\psi(\Gamma_{g;p_1,\ldots,p_r})$  into  $G_m$ . The correspondence  $\psi \mapsto \delta_{\psi}$  defines a map

$$T_{g;p_1,\ldots,p_r} \to S^m(t)$$
.

According to Theorem 6.2 this map is surjective. Let  $\operatorname{Mod}_{g;p_1,\dots,p_r}^m(t)$  be the subgroup of  $\operatorname{Aut}(P_{\psi}) = \operatorname{Mod}_{g;p_1,\dots,p_r}$  that preserves the m-Arf function  $\sigma_{\psi}$ . For any point in  $S^m(t)$  its pre-image in  $T_{g;p_1,\dots,p_r}$  consists of an orbit of the subgroup  $\operatorname{Mod}_{g;p_1,\dots,p_r}^m(t)$ . Thus

$$S^m(t) = T_{g;p_1,\dots,p_r} / \operatorname{Mod}_{g;p_1,\dots,p_r}^m(t). \quad \Box$$

Summarizing the results of Theorems 6.2 and 6.5 we obtain the following

#### Theorem 6.6.

- 1) Two hyperbolic GQHSS are in the same connected component of the space of all hyperbolic GQHSS if and only if they are of the same type. In other words, the connected components of the space of all hyperbolic GQHSS are those sets  $S^m(t)$  that are not empty.
- 2) The set  $S^m(t)$  is not empty if and only if  $t = (g, p_1, \ldots, p_r, \delta)$  has the following properties:
  - (a) The orders  $p_1, \ldots, p_r$  are prime with m and satisfy the condition

$$(p_1 \cdots p_r) \cdot \left( \sum_{i=1}^r \frac{1}{p_i} - (2g-2) - r \right) \equiv 0 \operatorname{mod} m.$$

- (b) If g > 1 and m is odd then  $\delta = 0$ .
- (c) If g = 1 then  $\delta$  is a divisor of  $gcd(m, p_1 1, \dots, p_r 1)$ .
- (d) If g = 0 then  $\delta = 0$ .
- 3) Any connected component  $S^m(t)$  of the space of all hyperbolic GQHSS of level m and signature  $(g:p_1,\ldots,p_r)$  is homeomorphic to

$$\mathbb{R}^{6g-6+2r}/\operatorname{Mod}_{g;p_1,\dots,p_r}^m(t),$$

where  $\operatorname{Mod}_{g;p_1,...,p_r}^m(t)$  is a subgroup of finite index in the group  $\operatorname{Mod}_{g;p_1,...,p_r}$  and acts discretely on  $\mathbb{R}^{6g-6+2r}$ .

Remark. Q-Gorenstein singularities: A normal isolated singularity of dimension at least 2 is Q-Gorenstein if there is a natural number r such that the divisor  $r \cdot \mathcal{K}_X$  is defined on a punctured neighbourhood of the singular point by a function. Here  $\mathcal{K}_X$  is the canonical divisor of X. According to [Pra07], hyperbolic Q-Gorenstein quasi-homogeneous surface singularities are in 1-to-1 correspondence with groups

of the form  $C^* \times \Gamma^*$ , where  $C^*$  is a lift of a finite cyclic group of order r into  $G_m$  and  $\Gamma^*$  is a lift of a Fuchsian group  $\Gamma$  into  $G_m$ . The lift of a finite cyclic group is unique, hence hyperbolic  $\mathbb{Q}$ -Gorenstein quasi-homogeneous surface singularities are are in 1-to-1 correspondence with lift of a Fuchsian group into  $G_m$ . Thus the moduli space of hyperbolic  $\mathbb{Q}$ -Gorenstein quasi-homogeneous surface singularities coincides with the moduli space of hyperbolic Gorenstein quasi-homogeneous surface singularities as described in Theorem 6.6.

Remark. Spherical and Euclidean Automorphy Factors: For a spherical Gorenstein automorphy factor ( $\mathbb{C}\operatorname{P}^1,\Gamma,L$ ) the group of automorphisms is  $\operatorname{Aut}(U)=\operatorname{Aut}(\mathbb{C}\operatorname{P}^1)=\operatorname{PSU}(2)$ . The discrete (and hence) finite subgroups of  $\operatorname{PSU}(2)$  are the cyclic groups, the dihedral groups and the symmetry groups of the regular polyhedra, i.e. the tetrahedral, octahedral and icosahedral groups. The corresponding singularities are  $A_k$ ,  $D_k$ ,  $E_6$ ,  $E_7$ ,  $E_8$ . For a Euclidean Gorenstein automorphy factor ( $\mathbb{C},\Gamma,L$ ) the group  $\Gamma$  is contained in the translation subgroup of  $\operatorname{Aut}(\mathbb{C})$  and can be identified with a sublattice  $\mathbb{Z}\cdot 1+\mathbb{Z}\cdot \tau$  of the additive group  $\mathbb{C}$ , where  $\tau\in\mathbb{C}$  and  $\operatorname{Im}(\tau)>0$ , see [Dol83b]. The corresponding singularities are  $\tilde{E}_6$ ,  $\tilde{E}_7$ ,  $\tilde{E}_8$ . All GQHSS other than  $A_k$ ,  $D_k$ ,  $E_6$ ,  $E_7$ ,  $E_8$ ,  $\tilde{E}_6$ ,  $\tilde{E}_7$ ,  $\tilde{E}_8$  belong to the class of hyperbolic GQHSS, which is studied in this paper.

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